

Design of efficient ground based soil moisture monitoring networks using cosmic-ray neutron probes and space-time data fusion

Trenton E. Franz

Asst. Professor of Hydrogeophysics,
School of Natural Resources, University of Nebraska-Lincoln
Daugherty Water for Food Institute Faculty Fellow

With acknowledgements to: William Avery (MS Student), Catie Finkenbiner (UCARE Student), Tiejun Wang (Postdoc), Foad Foolad (PhD Student), Chase Johnson (Crop consultant), Darin Desilets (HydroInnova LLC), Gary Womack (HydroInnova LLC), and Luca Brocca (IRPI)

Funding provided by: CRREL through the Great Plains CESU, NSF EPSCOR FIRST, USGS104b, and UNL Layman Award

What have I learned since last years workshop and
where is my lab group going

- Producers in semi-arid to arid parts of Nebraska have real needs for pragmatic soil moisture monitoring solutions
 - Commodity prices dictate level of risk for new monitoring solutions
 - Must show monitoring solutions increase yield or reduce input costs

- Producers in semi-arid to arid parts of Nebraska have real needs for pragmatic soil moisture monitoring solutions
 - Commodity prices dictate level of risk for new monitoring solutions
 - Must show monitoring solutions increase yield or reduce input costs
- Current Irrigation technology is far beyond what we can manage
 - The precision agriculture water monitoring problem

- Producers in semi-arid to arid parts of Nebraska have real needs for pragmatic soil moisture monitoring solutions
 - Commodity prices dictate level of risk for new monitoring solutions
 - Must show monitoring solutions increase yield or reduce input costs
- Current Irrigation technology is far beyond what we can manage
 - The precision agriculture water monitoring problem
- We have a responsibility to come up with practical solutions for stakeholders if we want water security for future generations

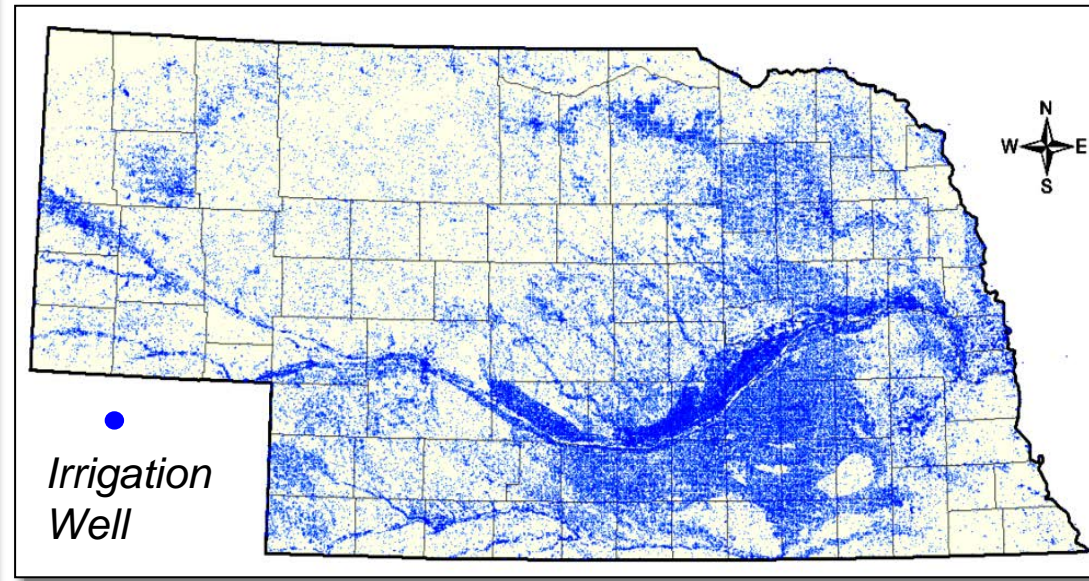
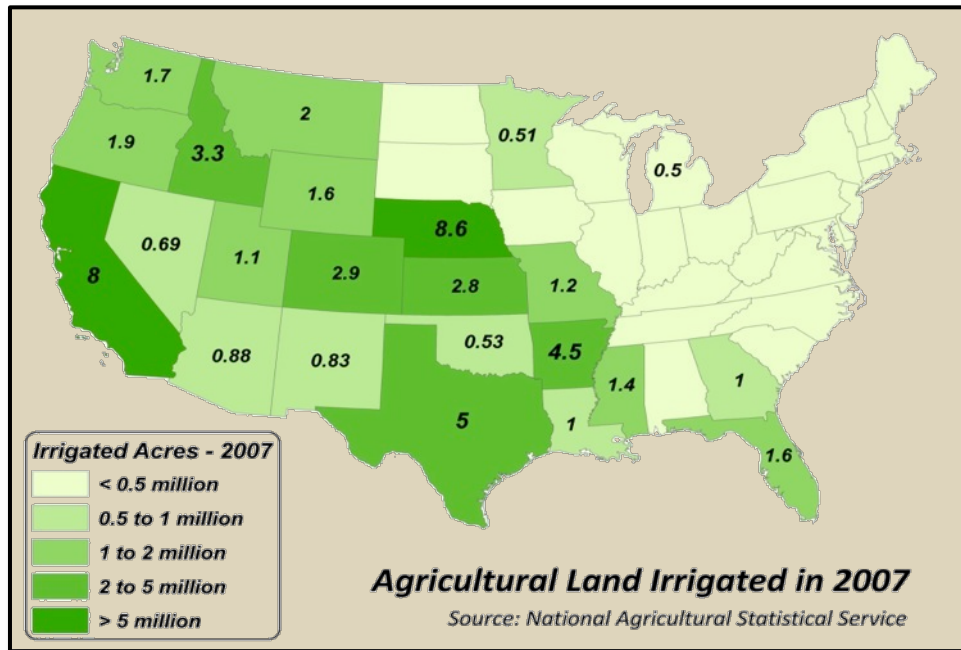
- Producers in semi-arid to arid parts of Nebraska have real needs for pragmatic soil moisture monitoring solutions
 - Commodity prices dictate level of risk for new monitoring solutions
 - Must show monitoring solutions increase yield or reduce input costs
- Current Irrigation technology is far beyond what we can manage
 - The precision agriculture water monitoring problem
- We have a responsibility to come up with practical solutions for stakeholders if we want water security for future generations
- The problem is complex but **solvable**
 - Apply new technologies in context of historical knowledge using multiple disciplines and incorporating existing infrastructure

- Producers in semi-arid to arid parts of Nebraska have real needs for pragmatic soil moisture monitoring solutions
 - Commodity prices dictate level of risk for new monitoring solutions
 - Must show monitoring solutions increase yield or reduce input costs
- Current Irrigation technology is far beyond what we can manage
 - The precision agriculture water monitoring problem
- We have a responsibility to come up with practical solutions for stakeholders if we want water security for future generations
- The problem is complex but **solvable**
 - Apply new technologies in context of historical knowledge using multiple disciplines and incorporating existing infrastructure
- Last years MOISST workshop led to new and fruitful areas of research

- Advanced center-pivot irrigation techniques can break apart field into 2 degree pie slices (Variable Speed, up to 180 management zones per field) and individual nozzle controls (Variable Rate, up to 5400 management zones field)
- **Clear need for developing pragmatic soil moisture monitoring techniques to harness existing irrigation technology for optimal water management**



~60,000 center-pivot irrigation systems in Nebraska alone!



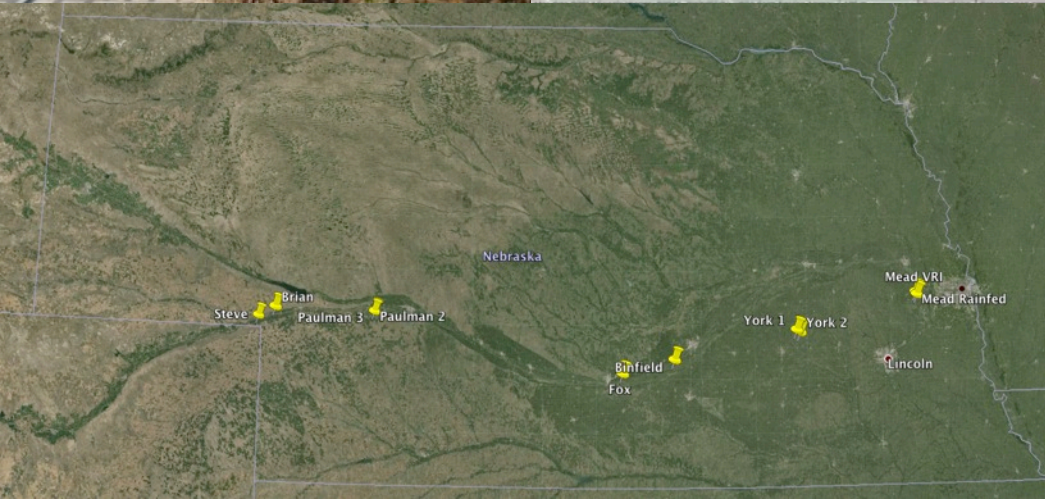
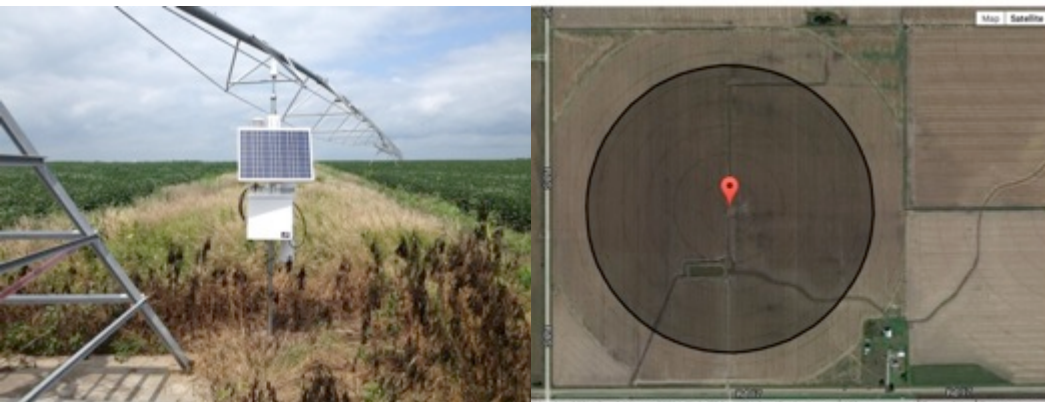
- 16% Of National Irrigated Land Is In Nebraska
- 90% Of Water Withdrawal Is For Irrigation

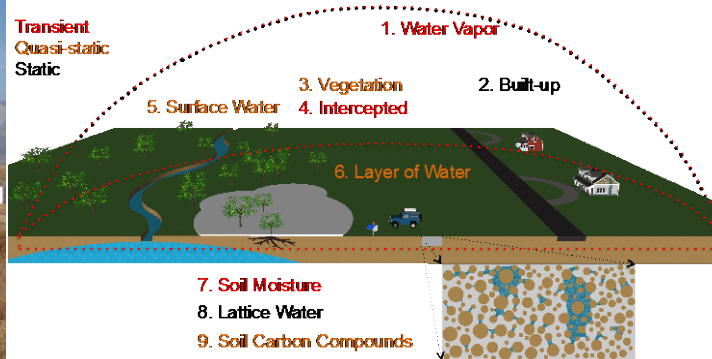
~ 93,000 Active Irrigation Wells
\$6-8 Billion Investment

Research: Understand the flow of water through natural and human dominated ecosystems

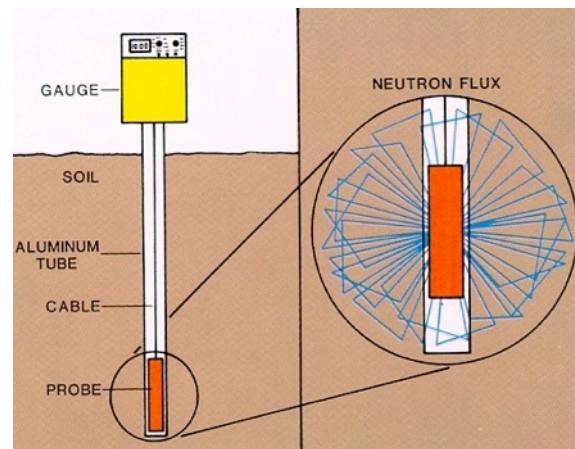
Extension: Expose or incorporate useful hydrogeophysical technologies into practice of stakeholders across the state.

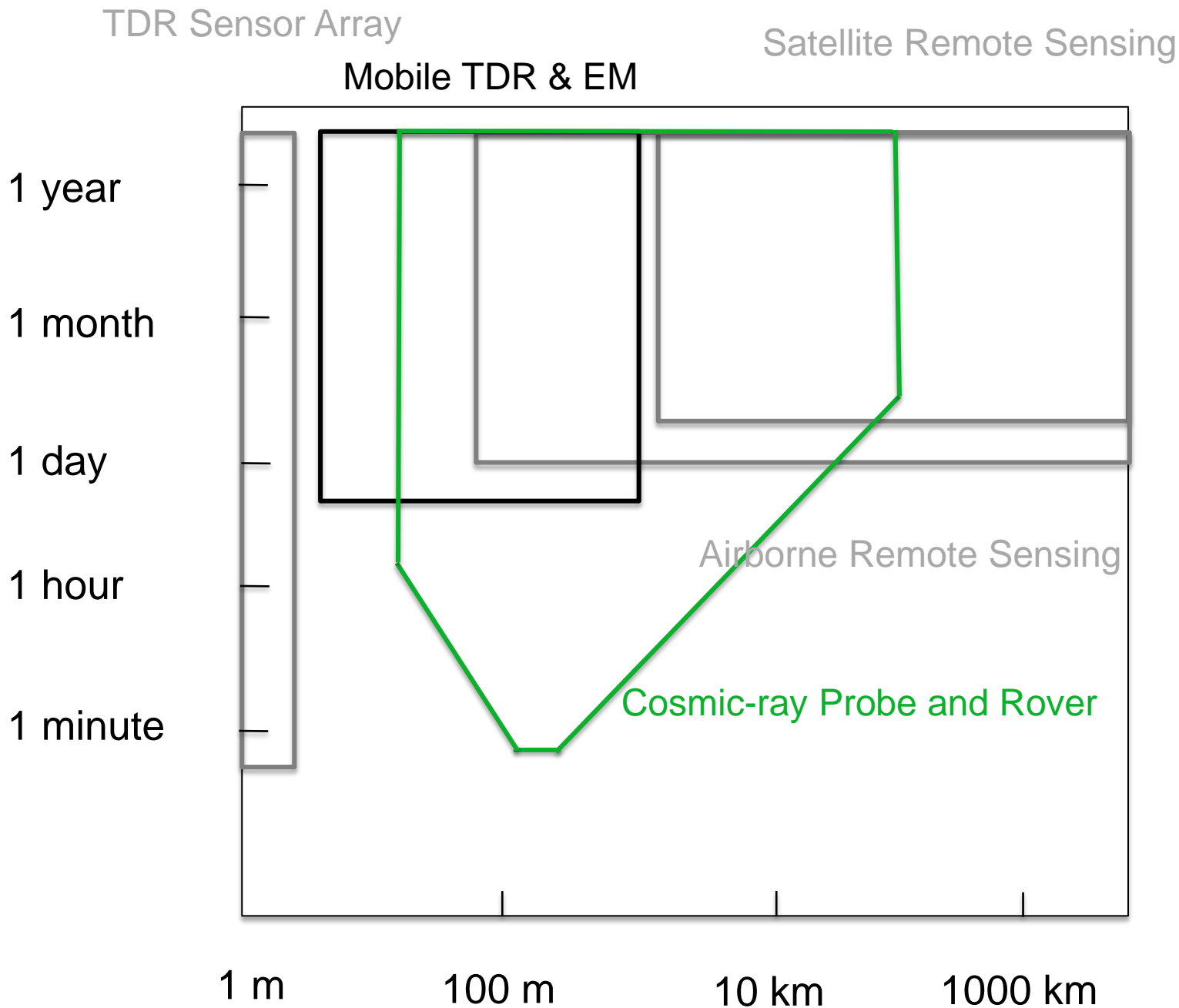
How many inches of water can this technology save?



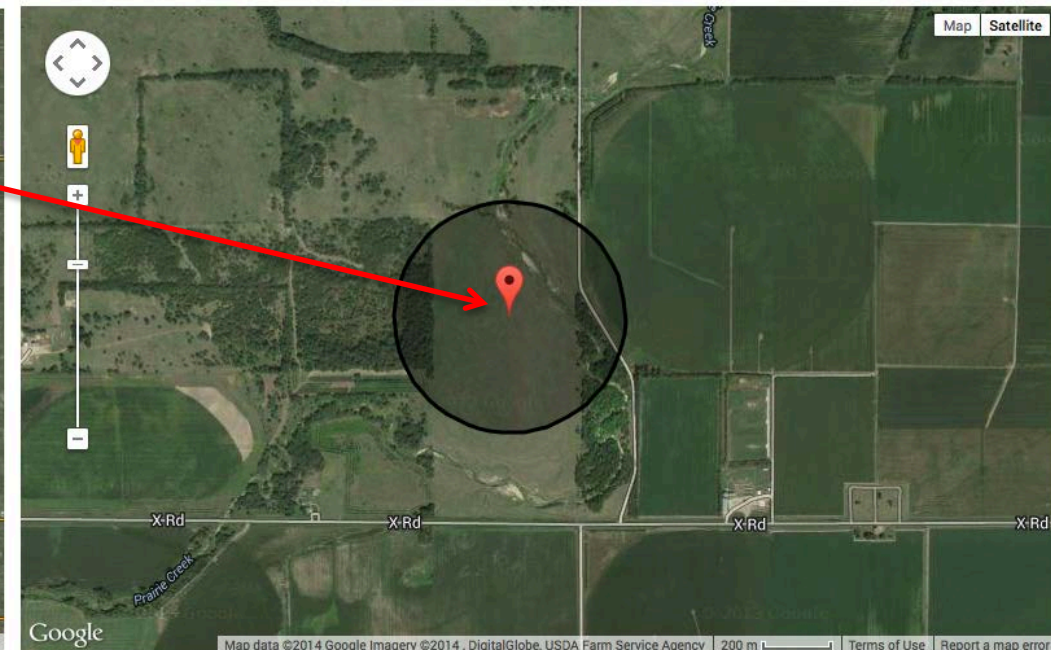
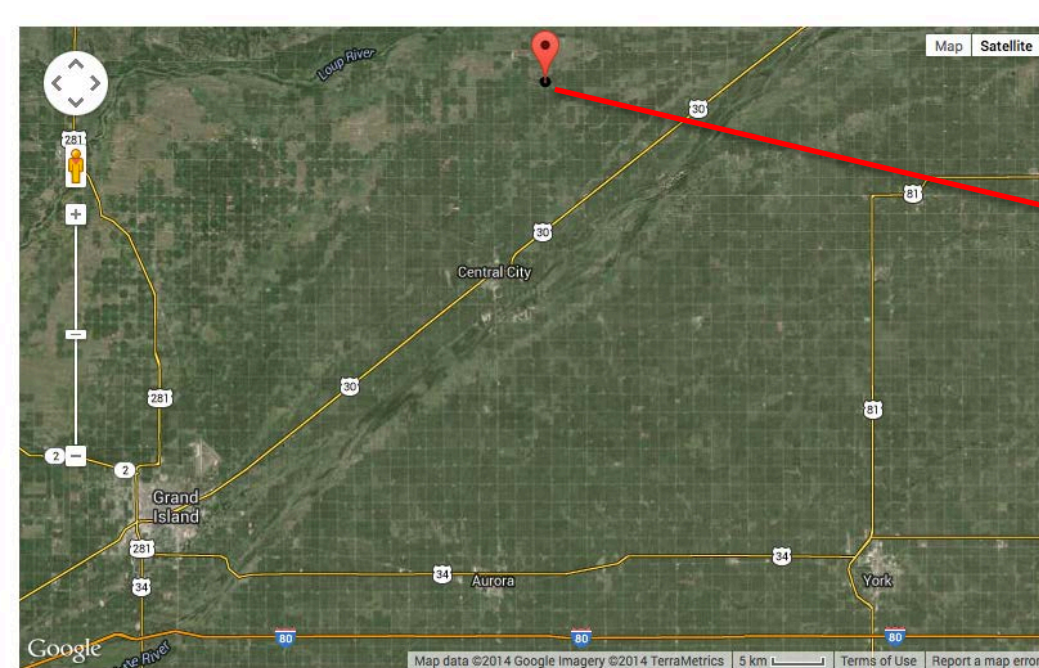


- Essentially same detector but with updated electronics and high voltage NPMs
- Same basic physics as in-situ neutron probe
- Passive sensor, uses cosmic-ray neutrons as source
- Relates fast neutrons to water content instead of slow or thermal neutrons
- Footprint is ~1000x larger (density of soil vs. air)
- Probe sees about top 30 cm
- **In-situ probe considered gold standard in agronomy and soil physics**

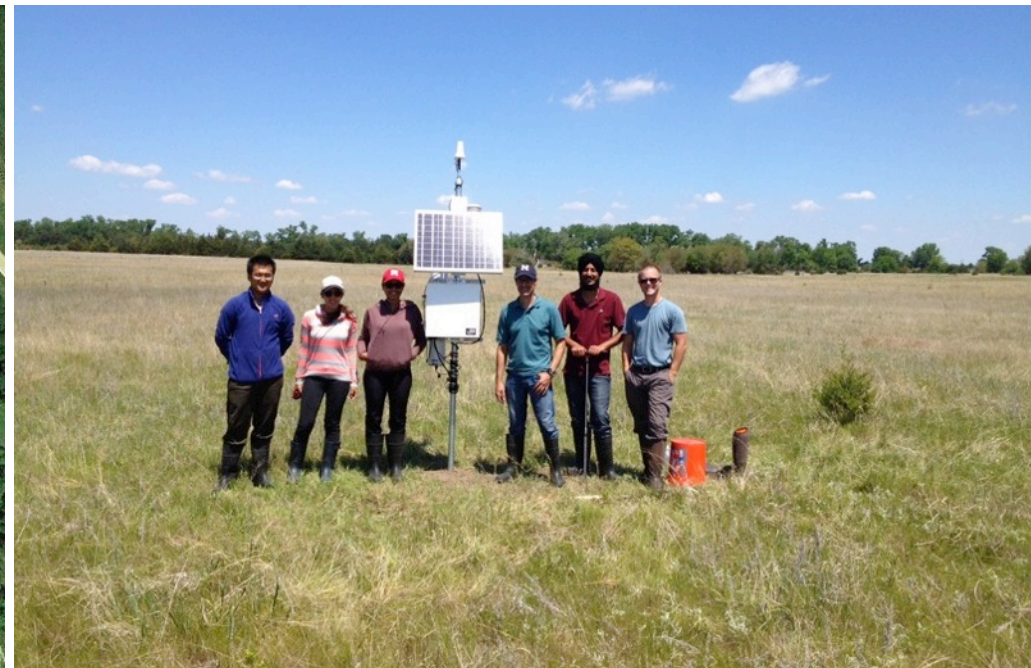
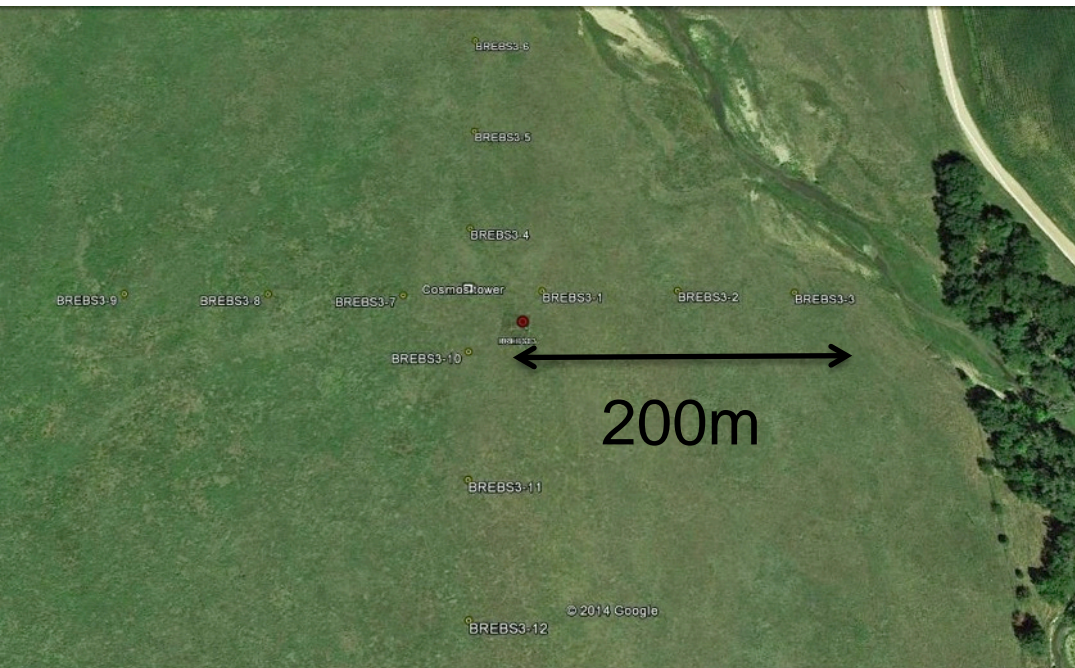


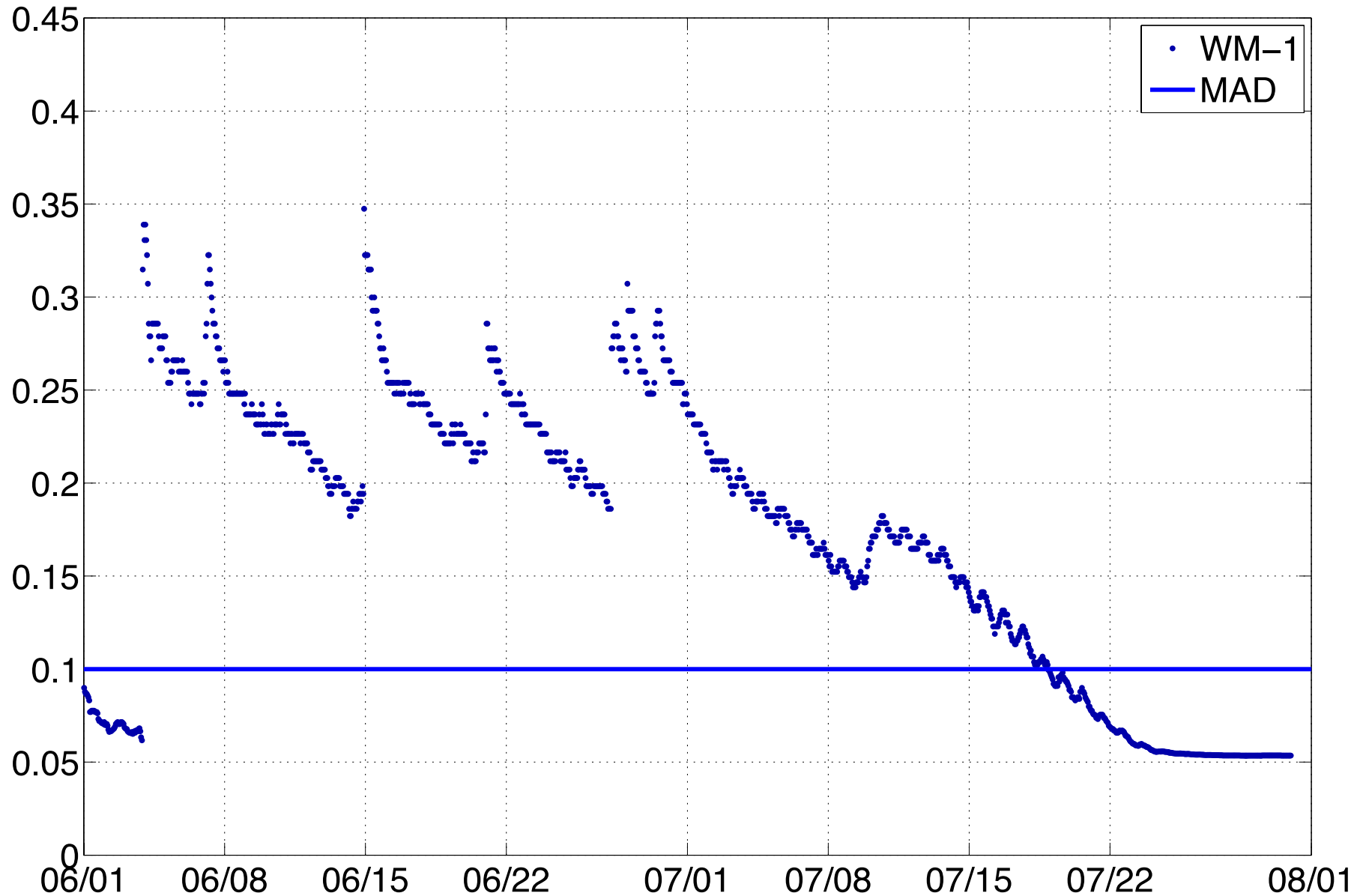


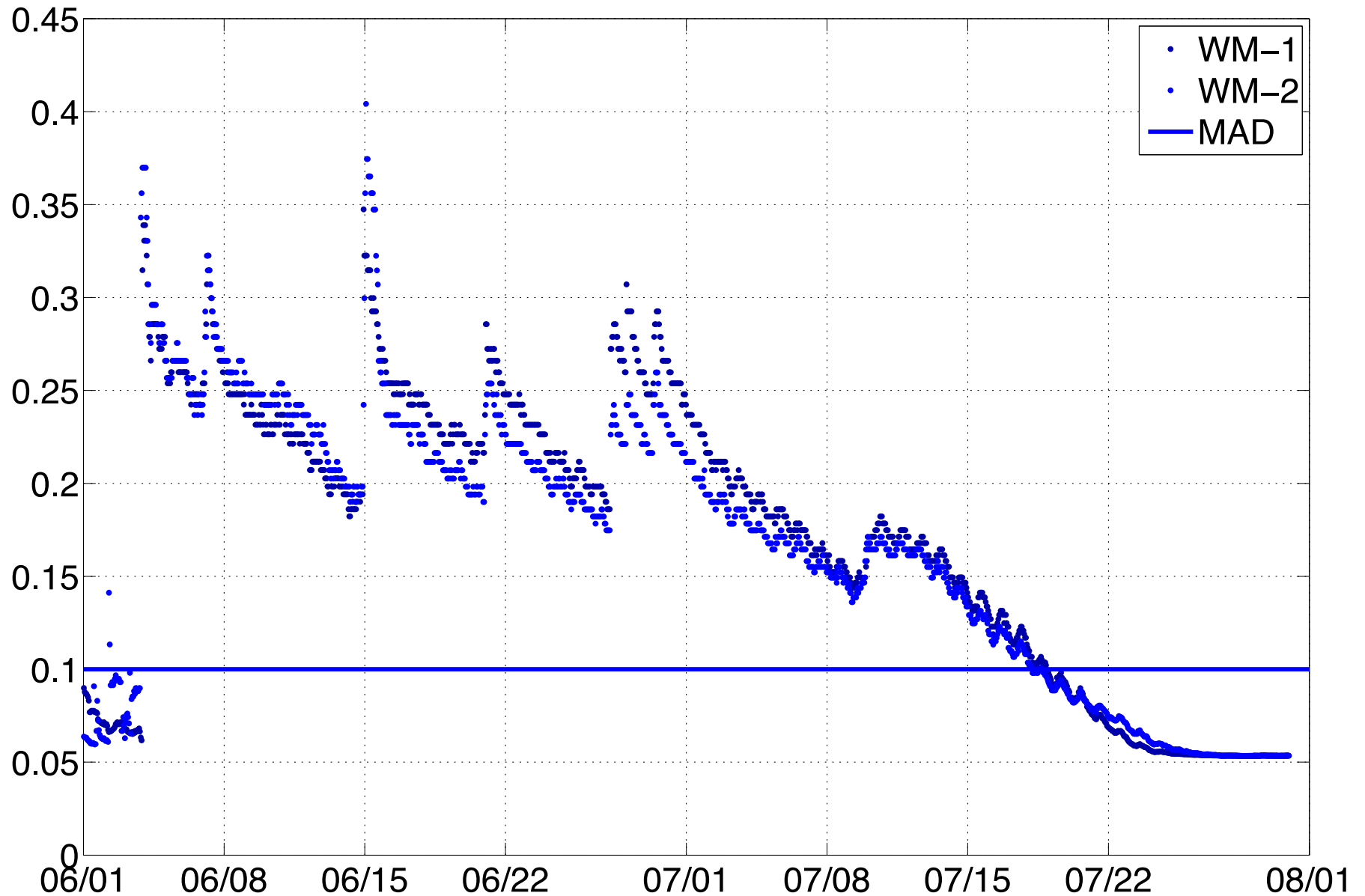
June-July 2014, near Central City, NE
Installed 12 profiles of Watermark sensors
and 1 cosmic-ray sensor

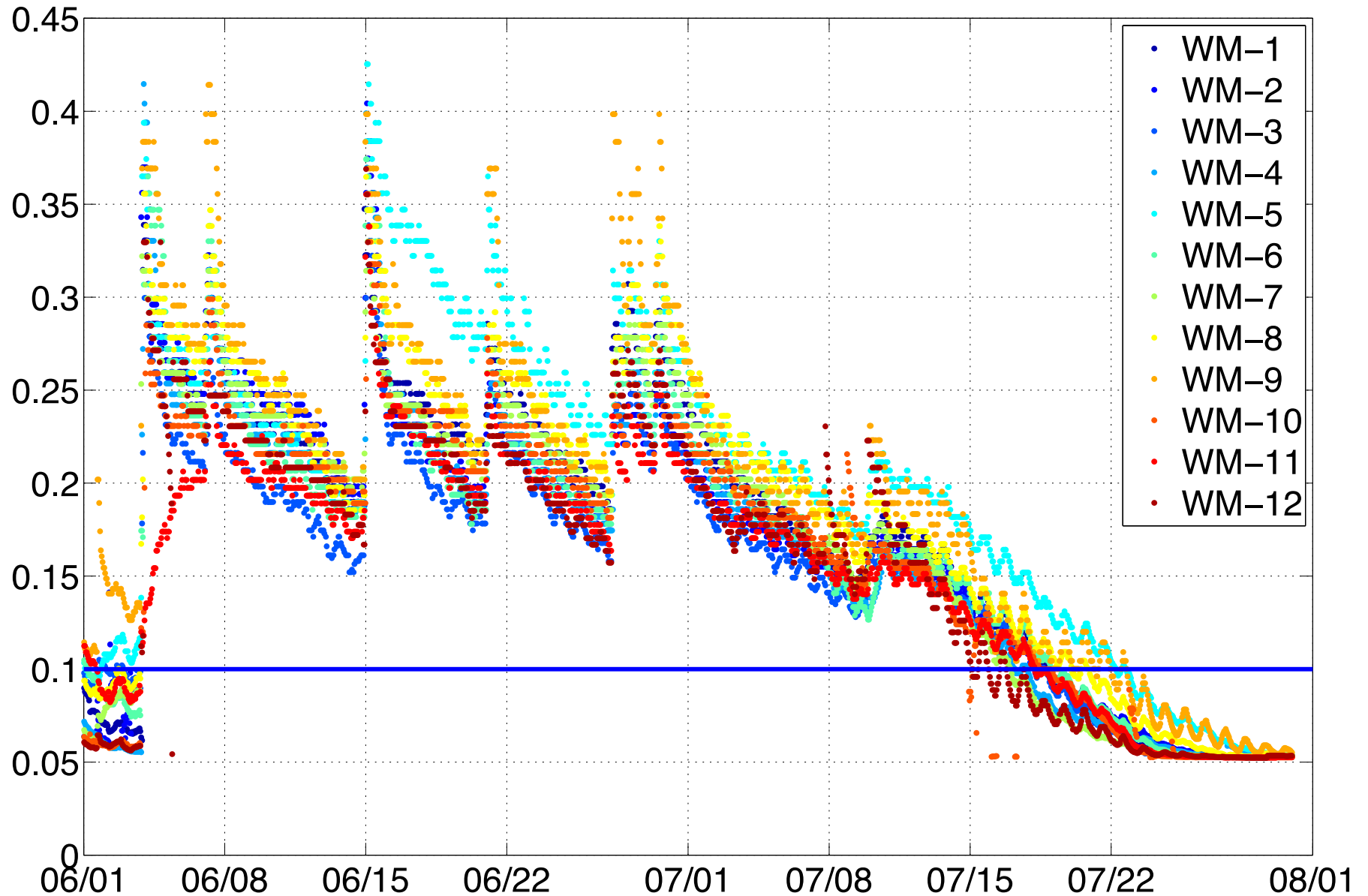


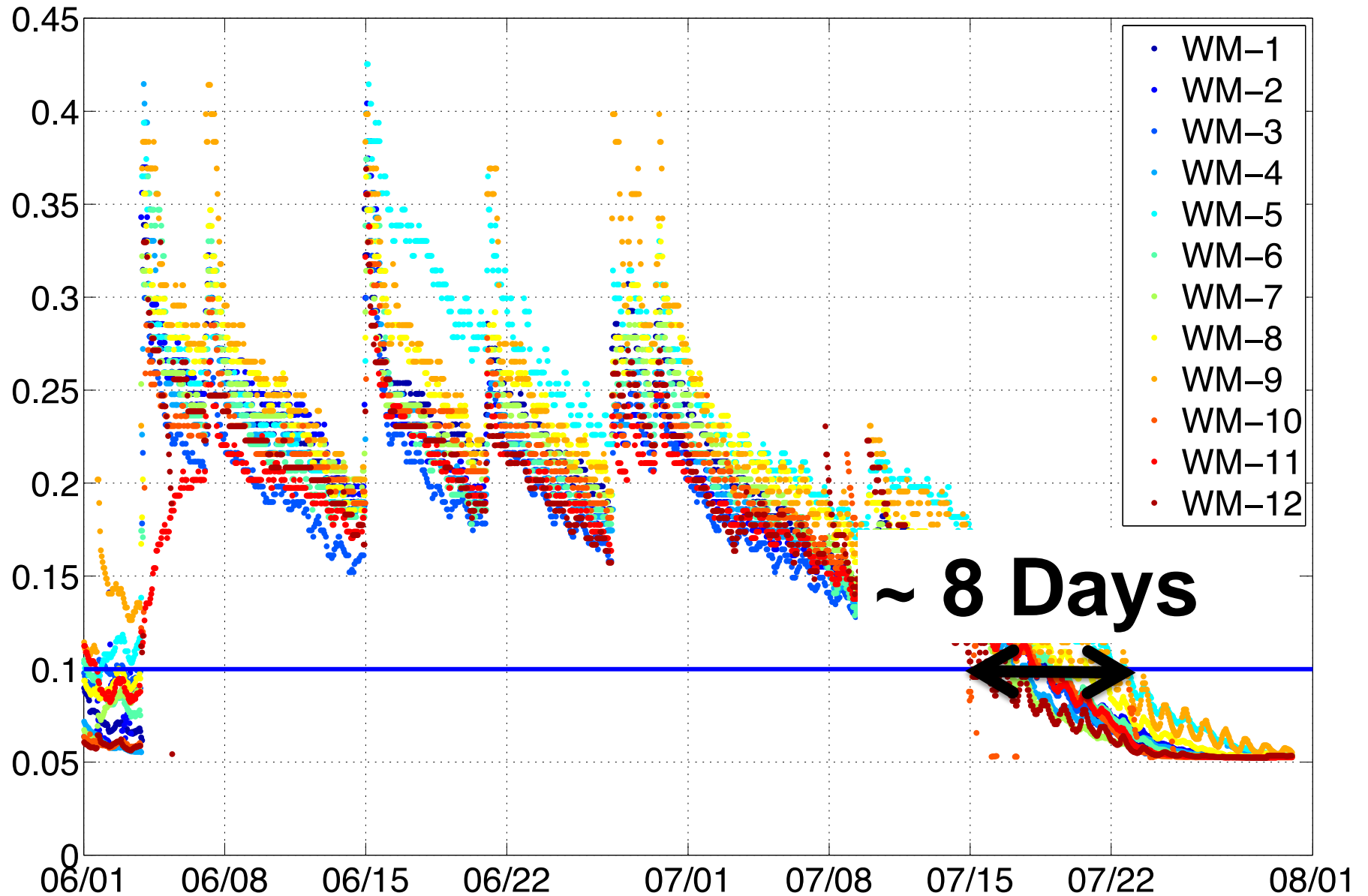
Field is fairly flat, homogeneous vegetation, sandy loam soil texture,
ideal setting for homogeneity?

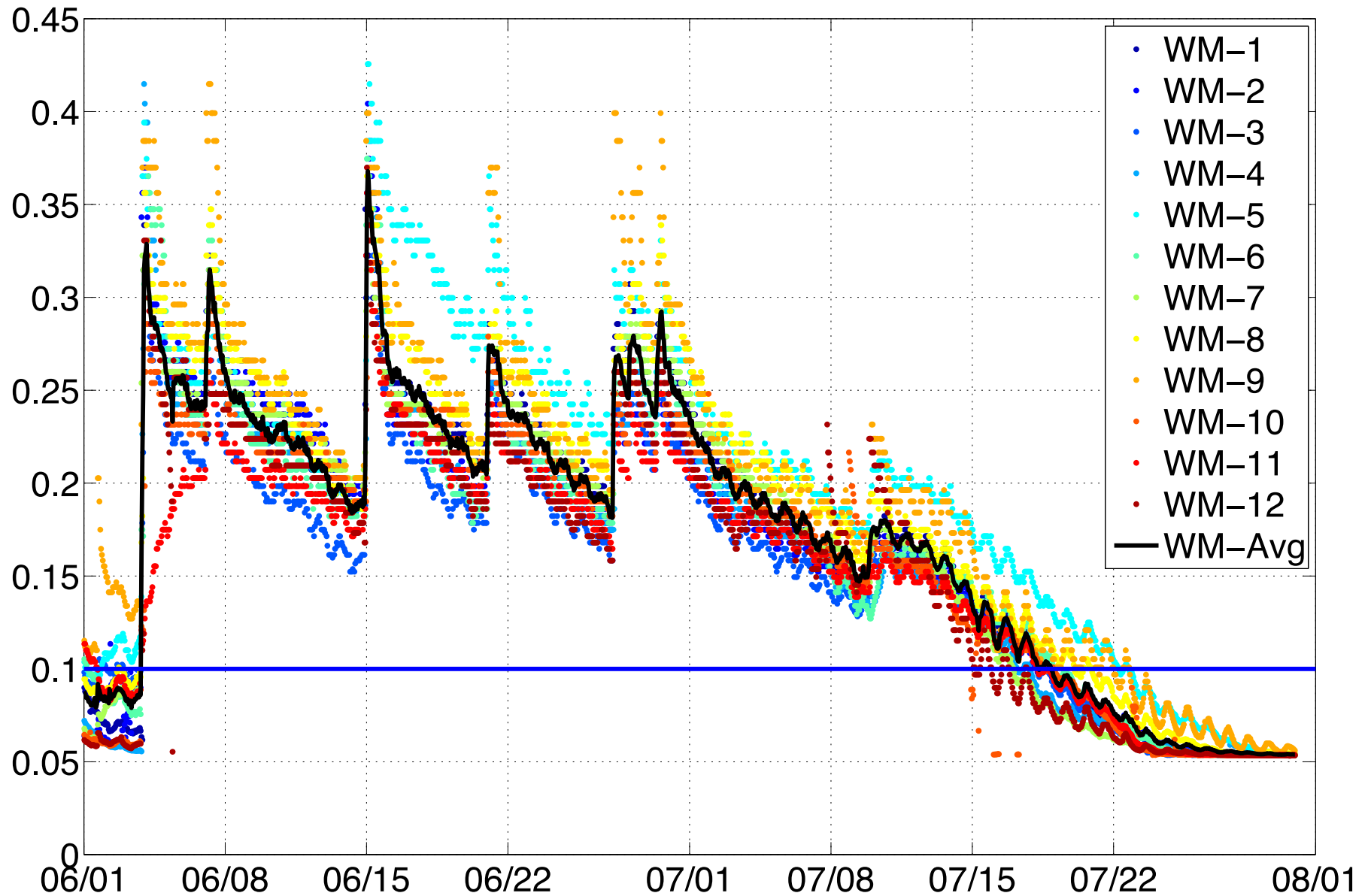


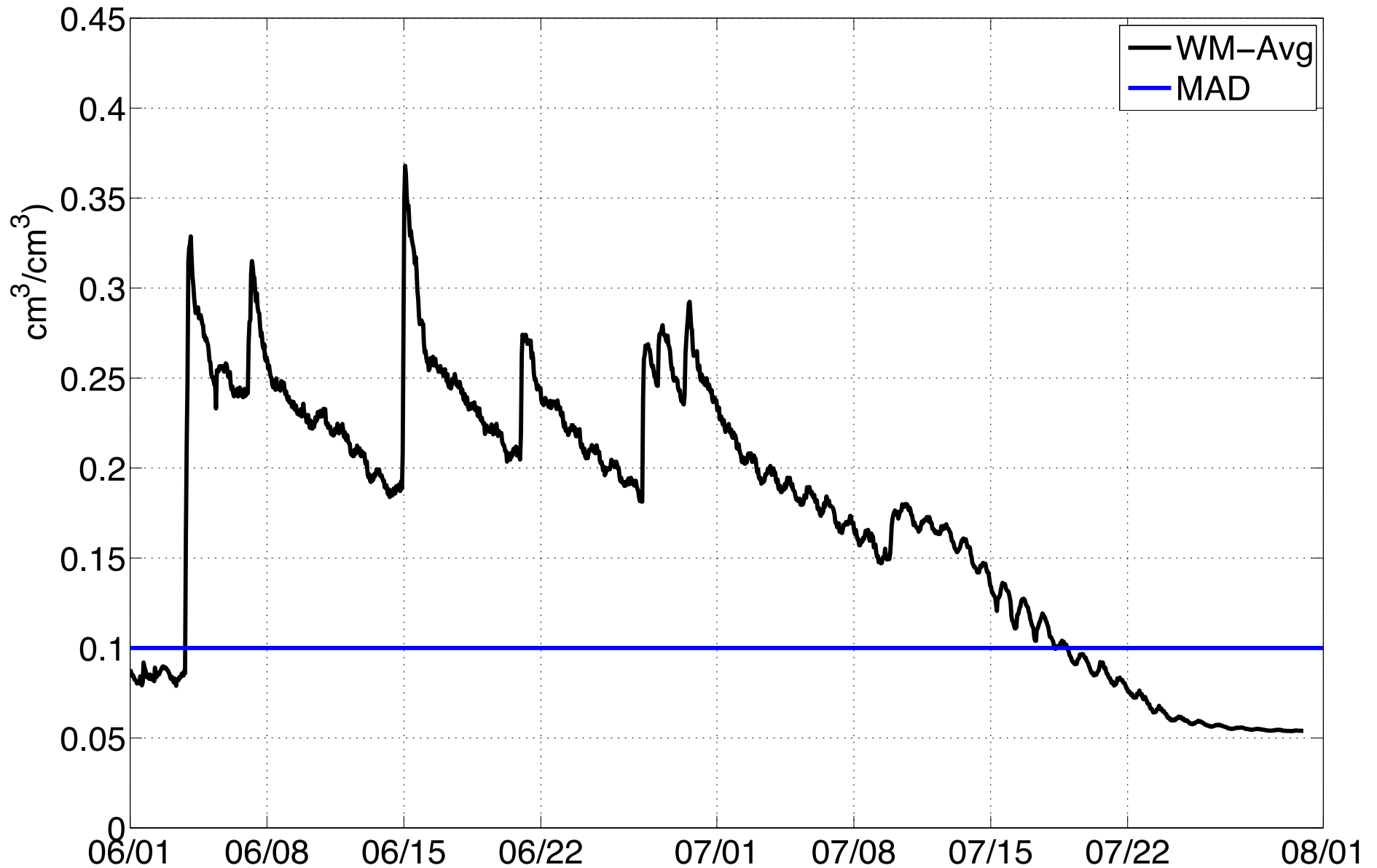


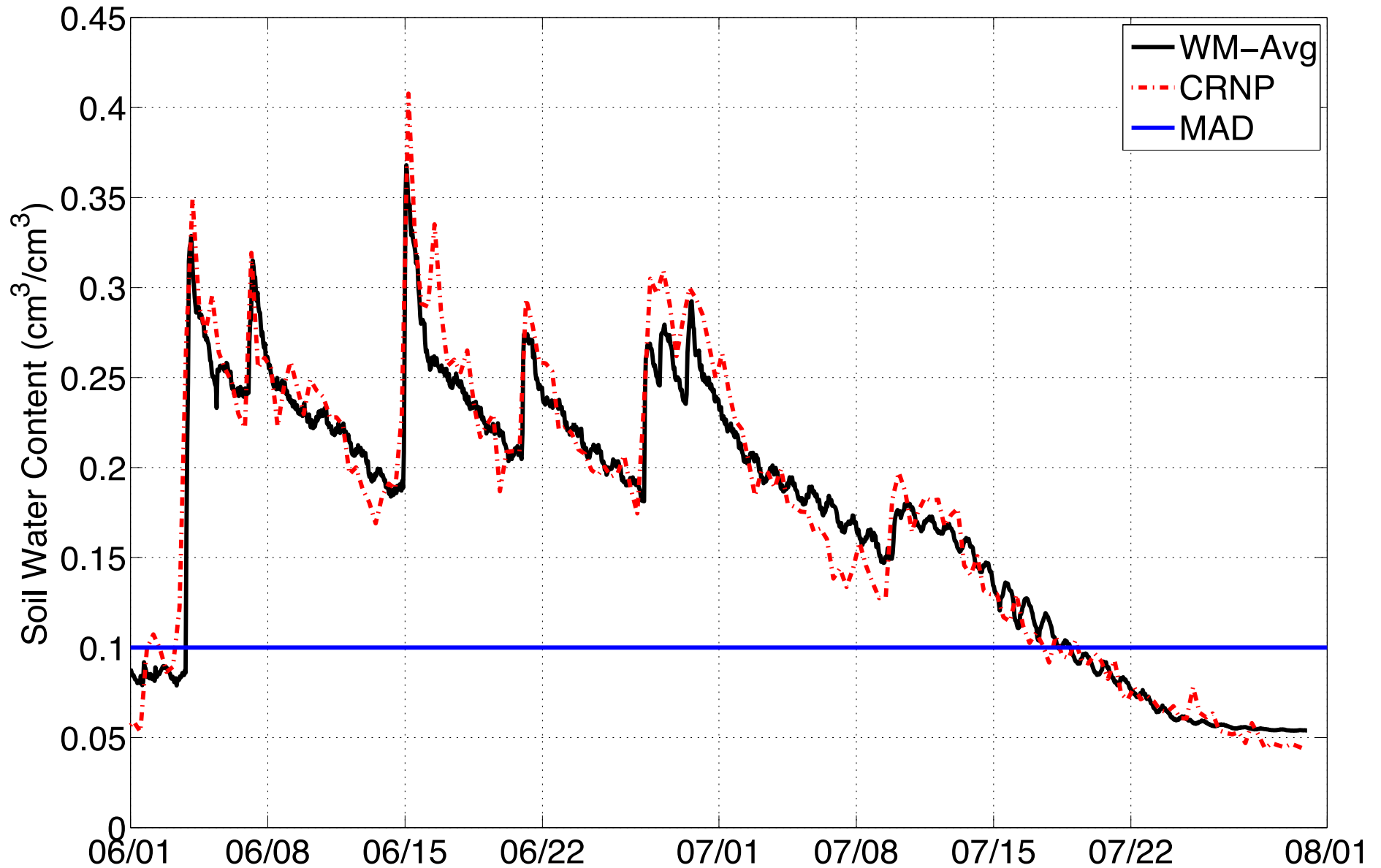


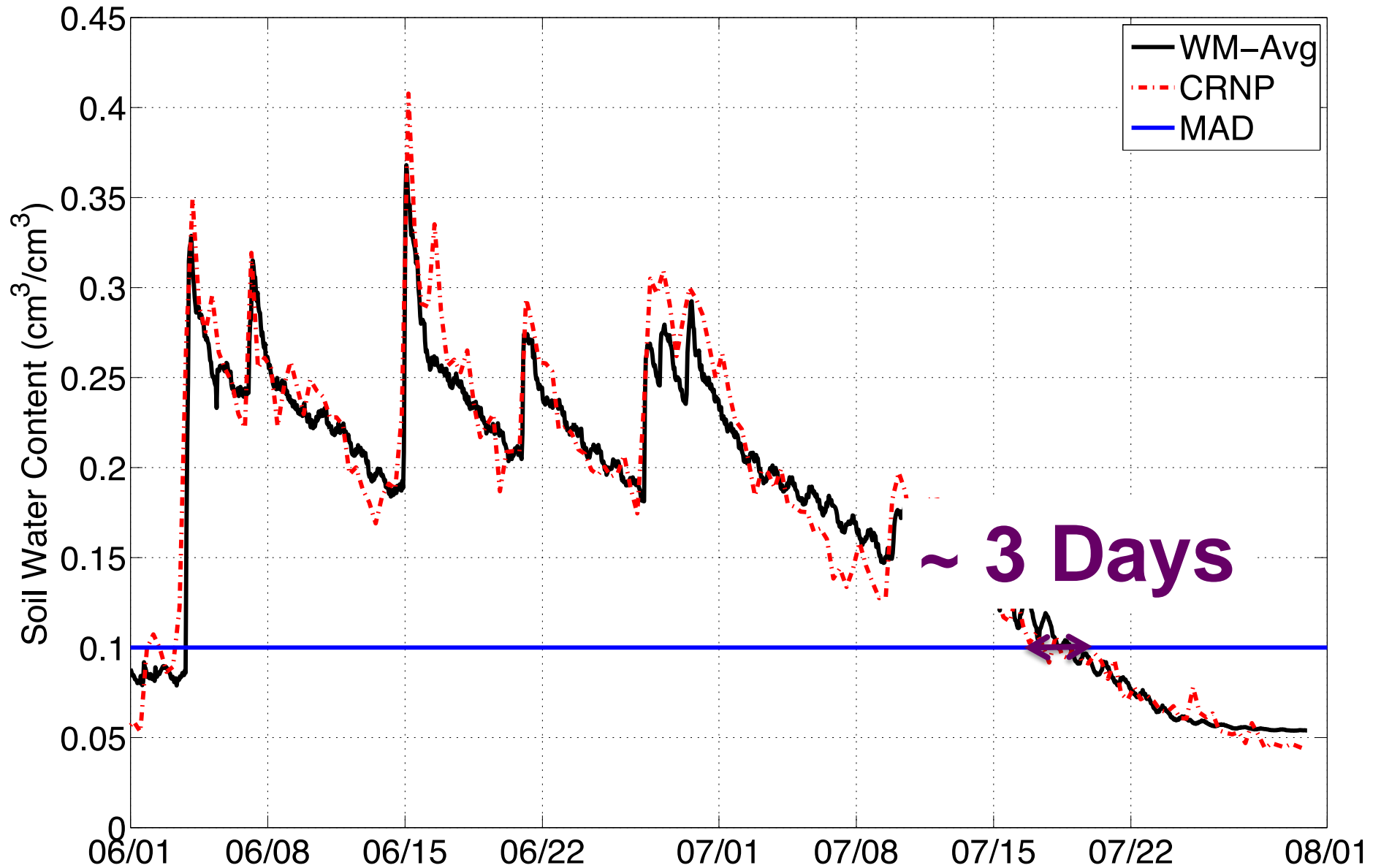




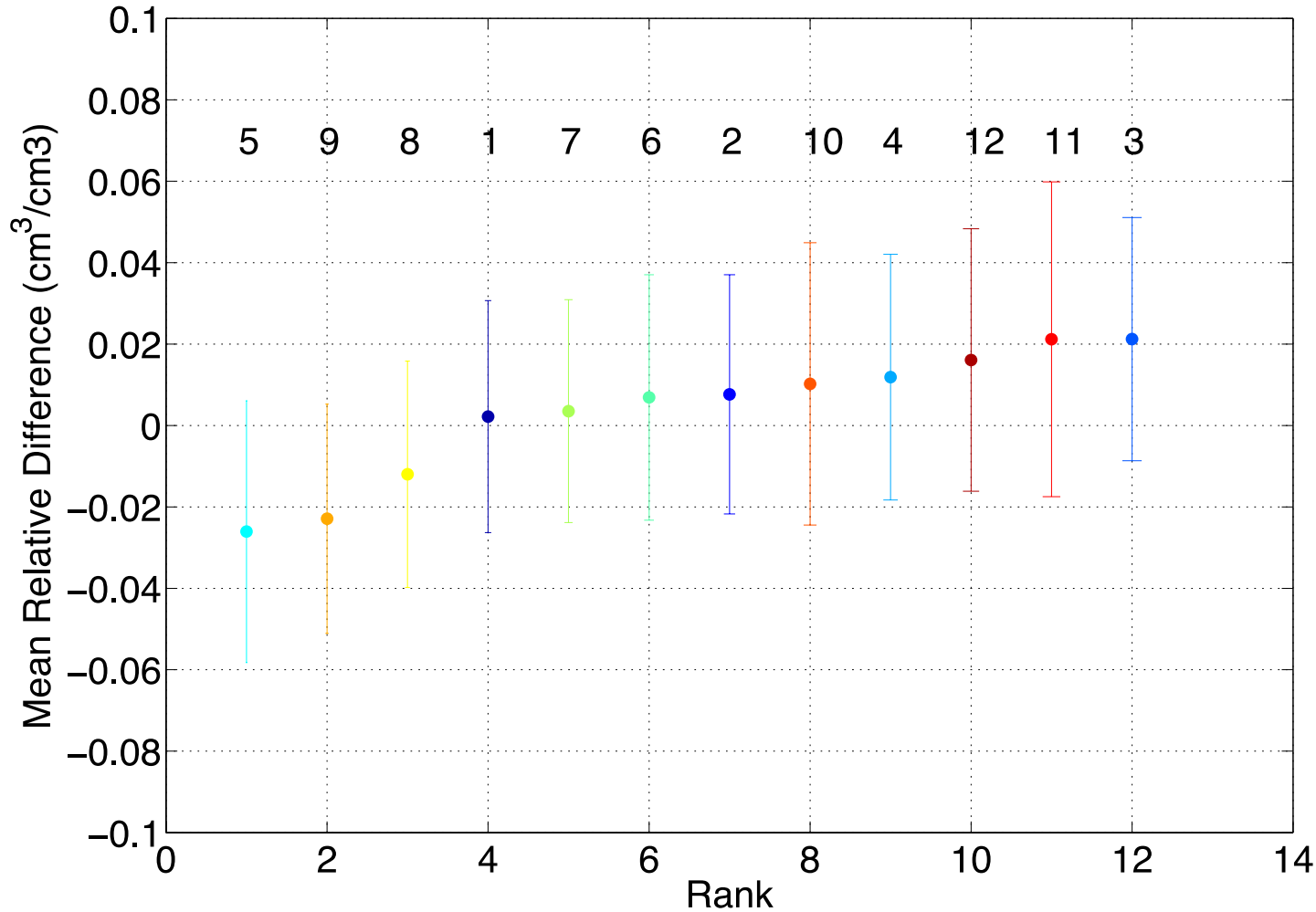








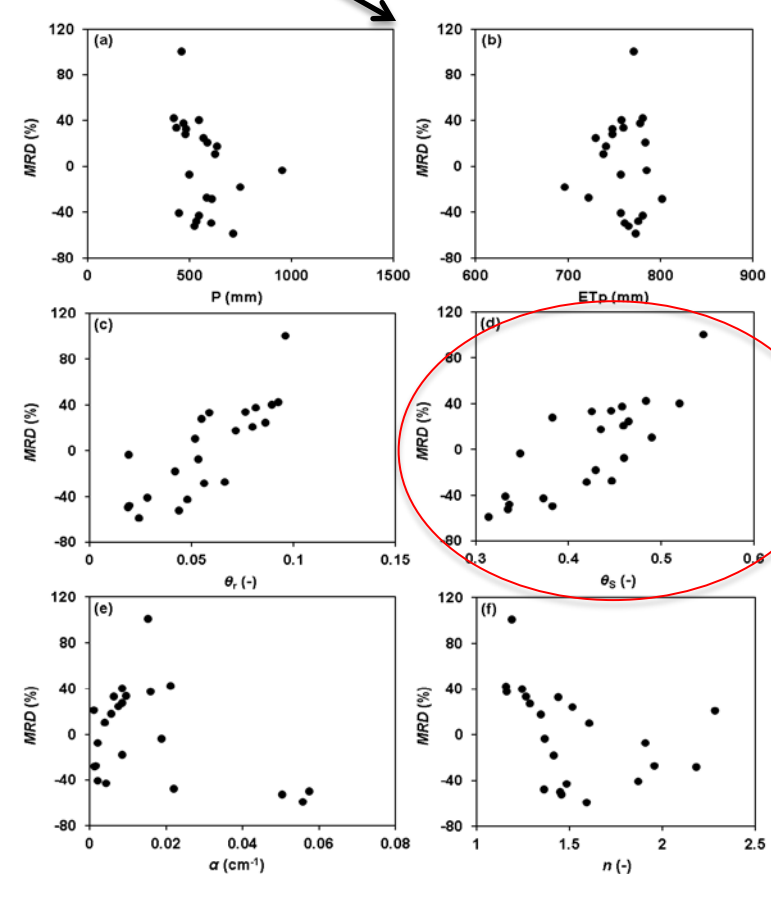
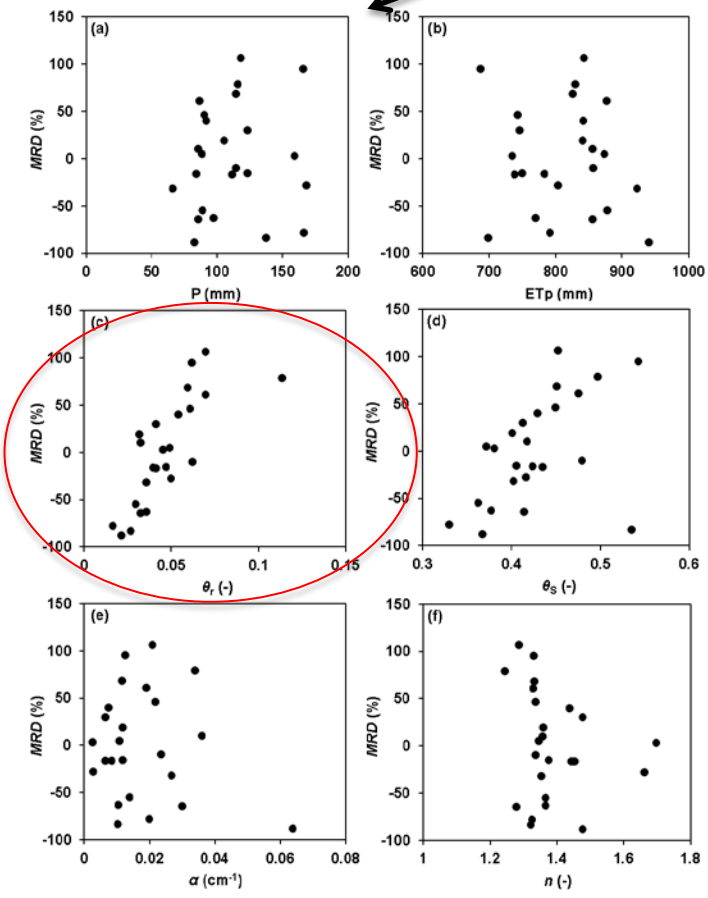
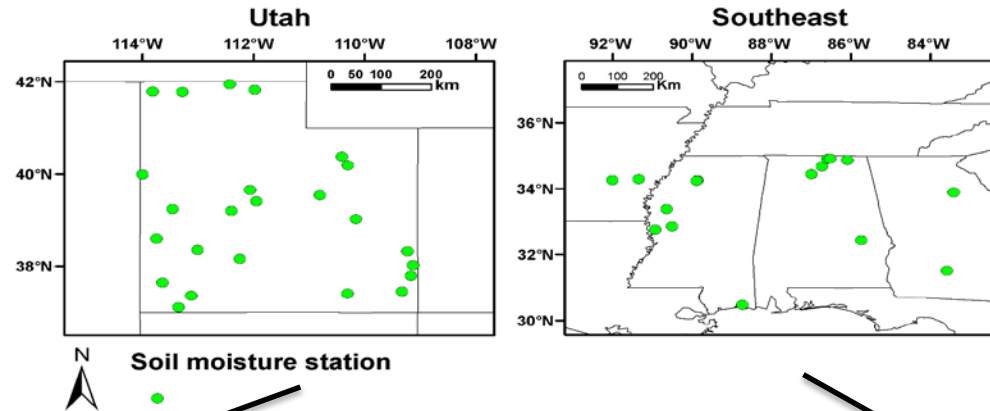
Temporal Stability Analysis

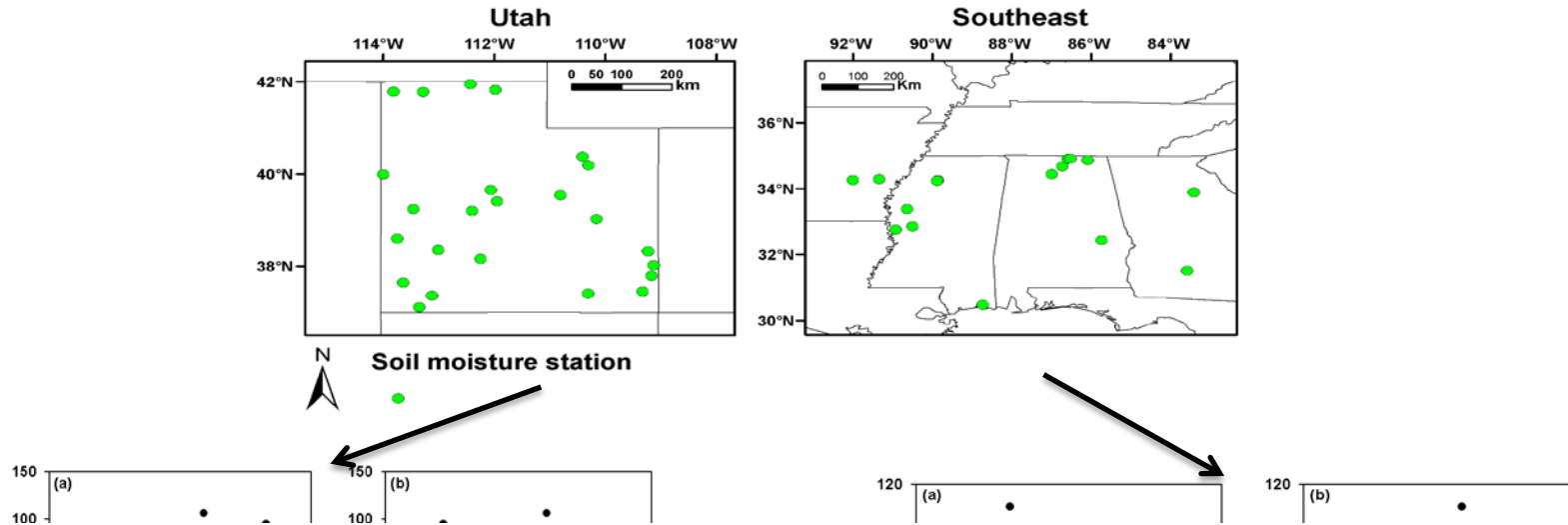


$$RD_{ij} = \frac{\theta_{ij} - \bar{\theta}_j}{\bar{\theta}_j}$$

$$MRD_i = \frac{1}{m} \sum_{j=1}^m RD_{ij}$$

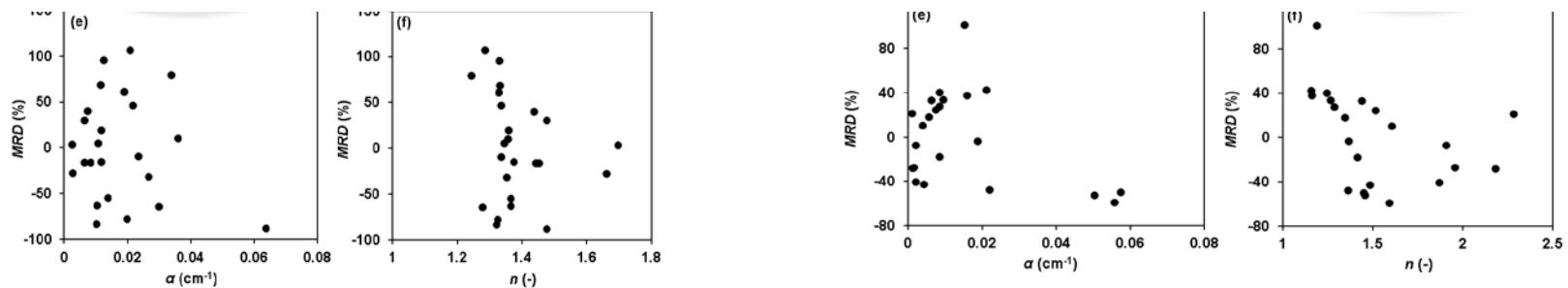
Following Vachaud et al. (1985) and others





Point scale soil moisture observations from SCAN mesonet shows MRD controlled by soil texture/hydraulic properties instead of climatology as previously thought.

Why?

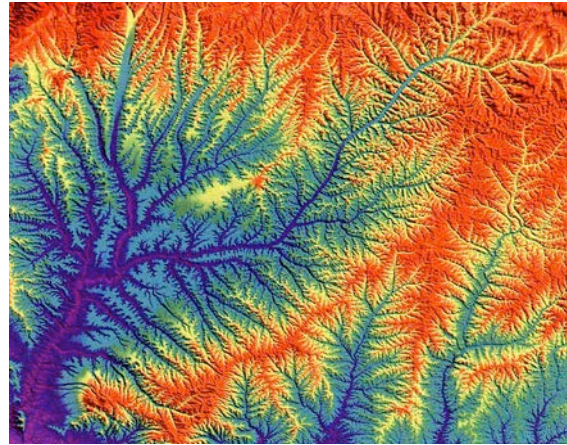


Canopy and Root Architecture



Koiya Group Ranch, Kenya, Feb. 2007

River Basins/Channel Networks



GEOPHYSICAL RESEARCH LETTERS, VOL. 22, NO. 20, PAGES 2757-2760, OCTOBER 15, 1995

On the spatial organization of soil moisture fields

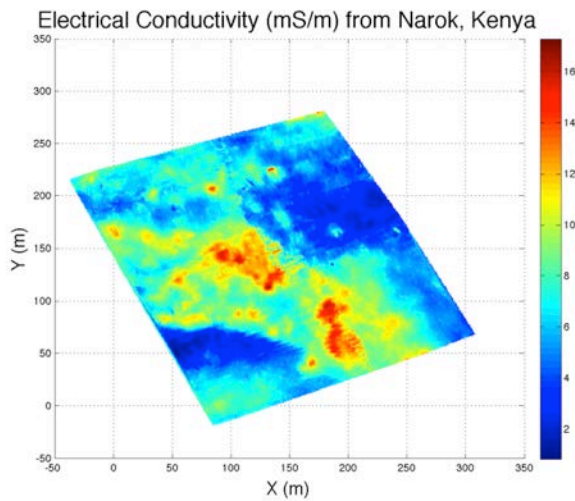
Ignacio Rodriguez-Iturbe, Gregor K. Vogel, Riccardo Rigon¹
Department of Civil Engineering, Texas A&M University, College Station, Texas

Dara Entekhabi
Department of Civil and Environmental Engineering, M.I.T., Cambridge, Massachusetts

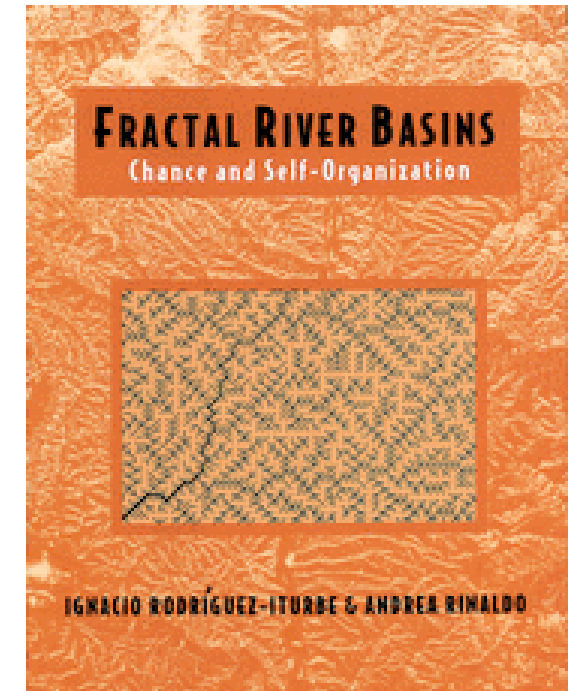
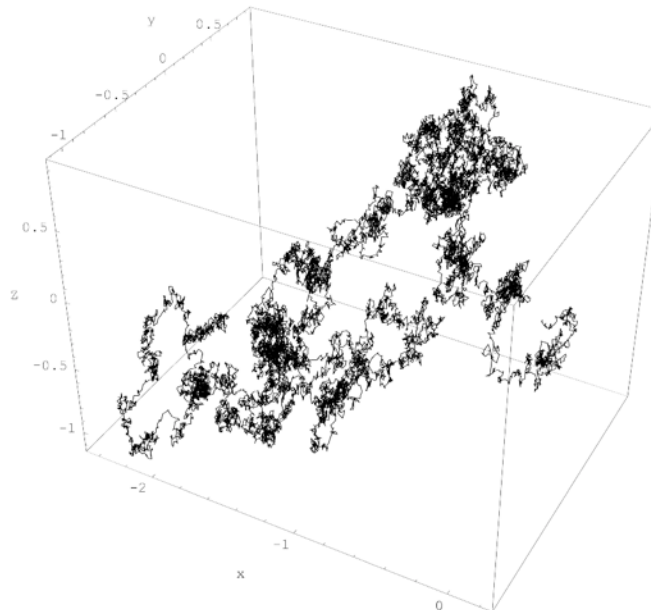
Fabio Castelli
Istituto di Idraulica, Università di Perugia, Perugia, Italy

Andrea Rinaldo
Istituto di Idraulica "G. Pleni," Università di Padova, Padova, Italy

Soil Properties



Brownian Motion



Deployed 3 stationary CRS sensors recording hourly soil moisture in irrigated maize, soybean and rainfed maize/soybean near Waco, NE.

Used roving CRS to make daily soil moisture maps every week over a 12x12 km grid with 1.6 km spacing between May and September 2014.

Goal to make continuous soil moisture estimates at individual quarter section level (~0.8 km) using statistical methods

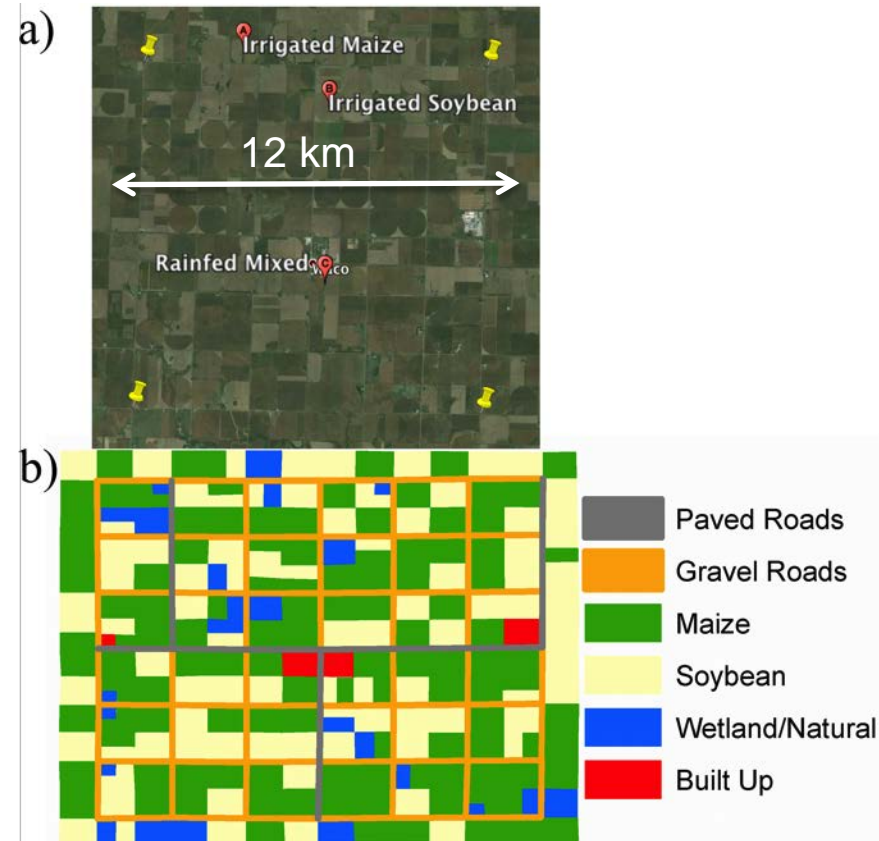
Roving Sensor



Stationary Sensor

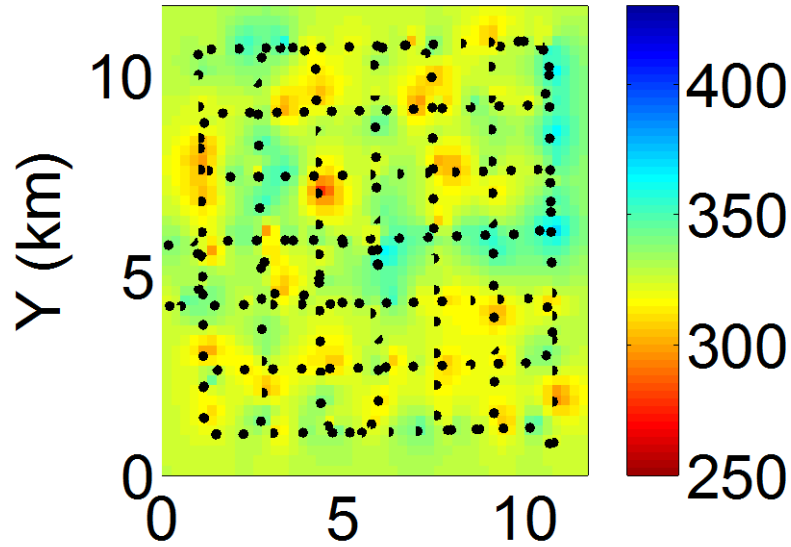


Study Area and Layout of Sensors

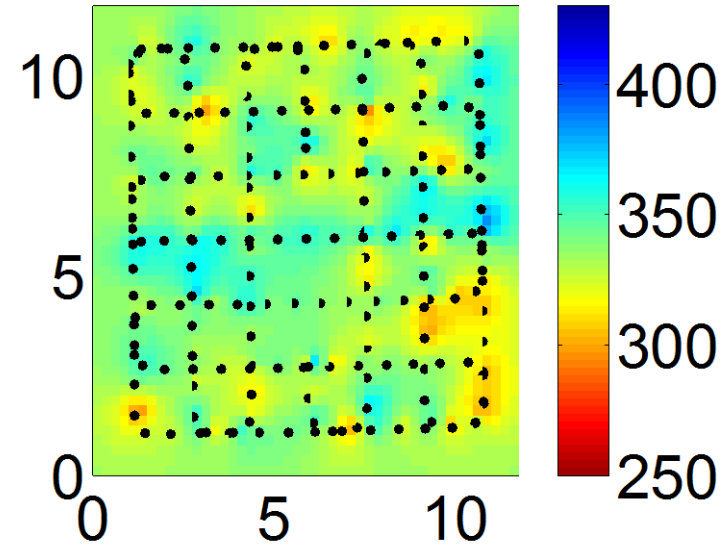


- Combine fixed and roving cosmic ray neutron soil moisture data sets
- Data merging techniques to design soil moisture network at different scales
- Soil moisture network can provide spatiotemporal data and stats for downscaling

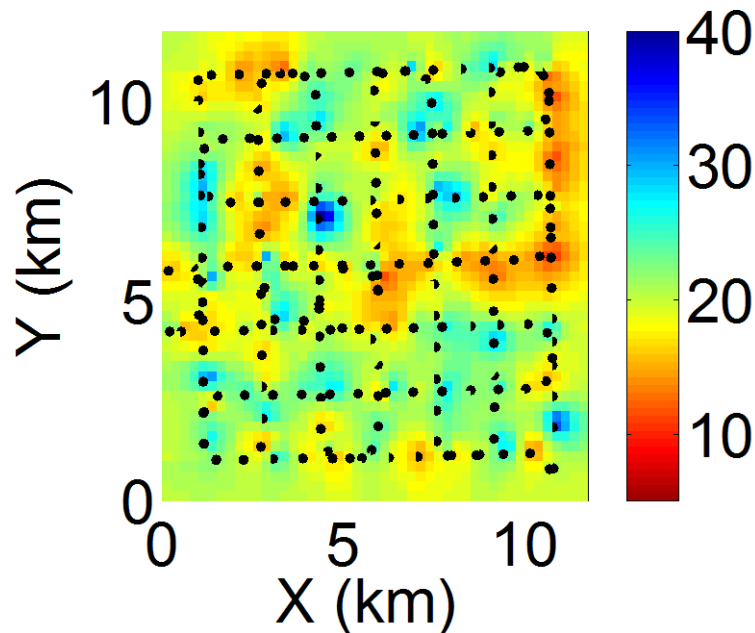
26 June 2014, N (cpm)



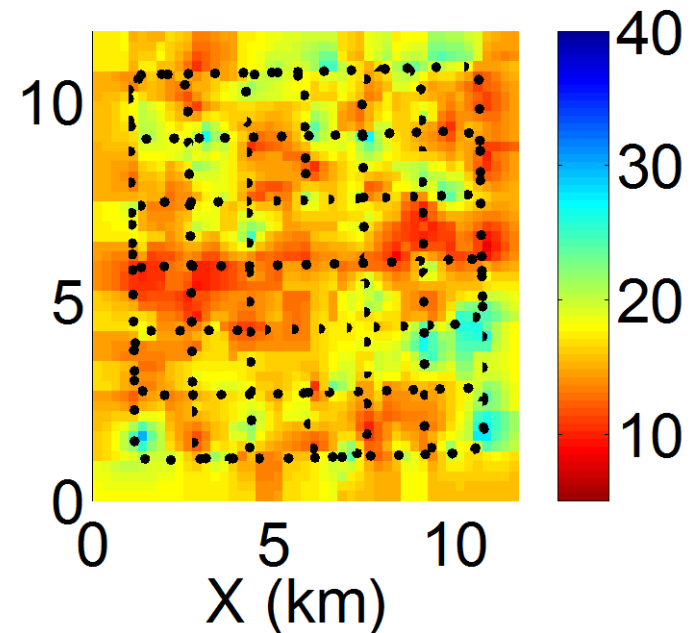
30 July 2014, N (cpm)

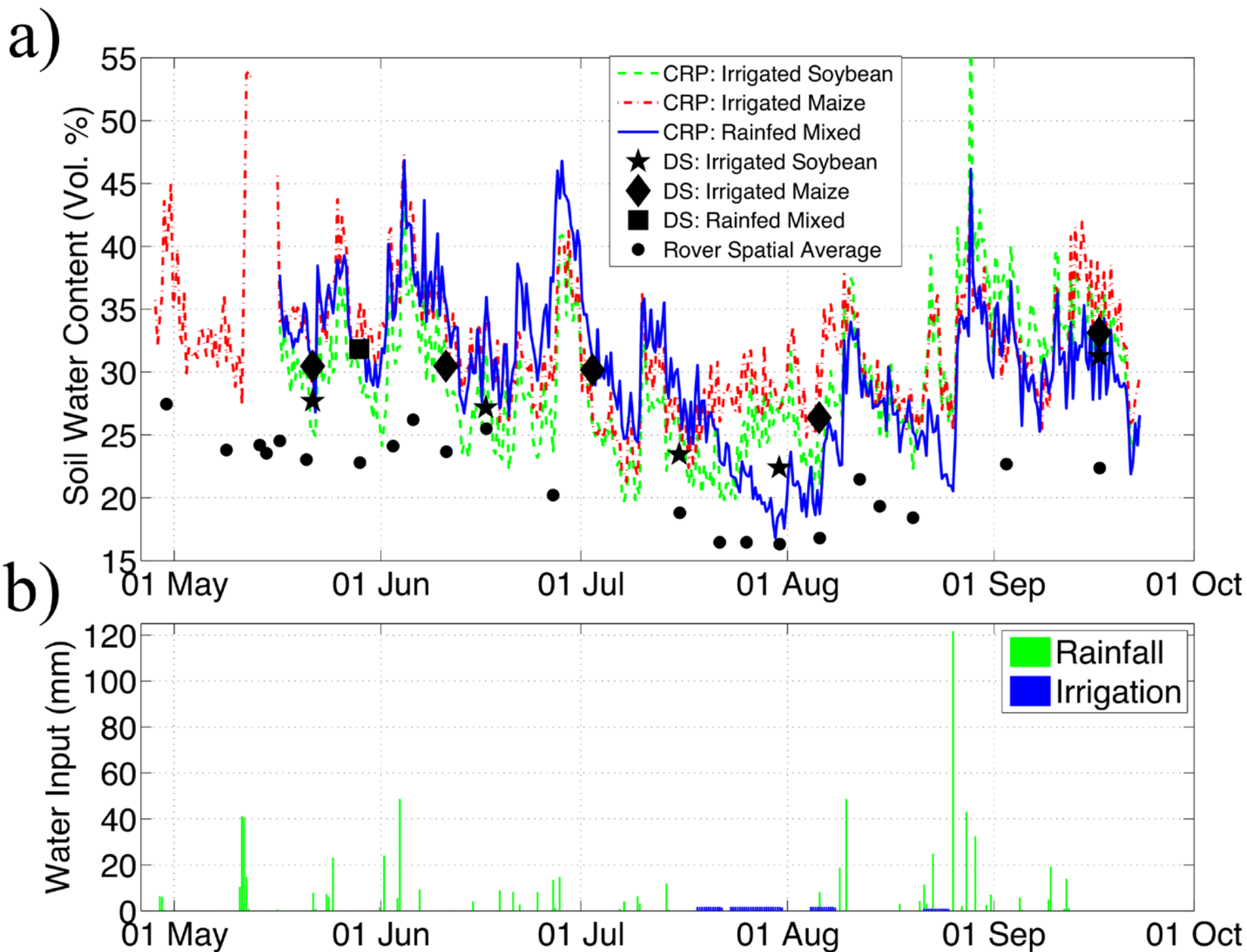


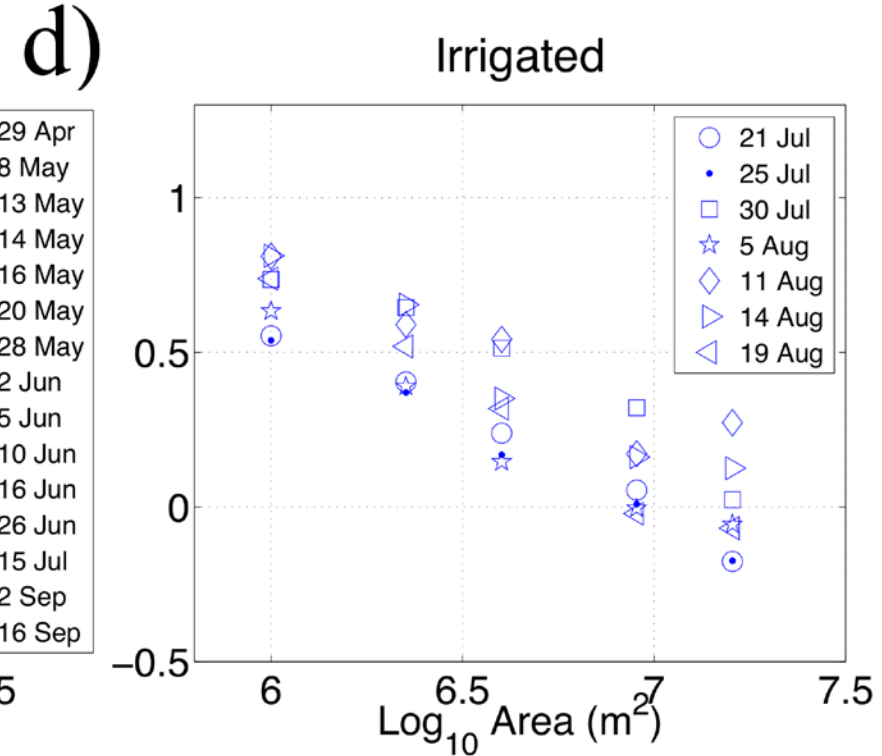
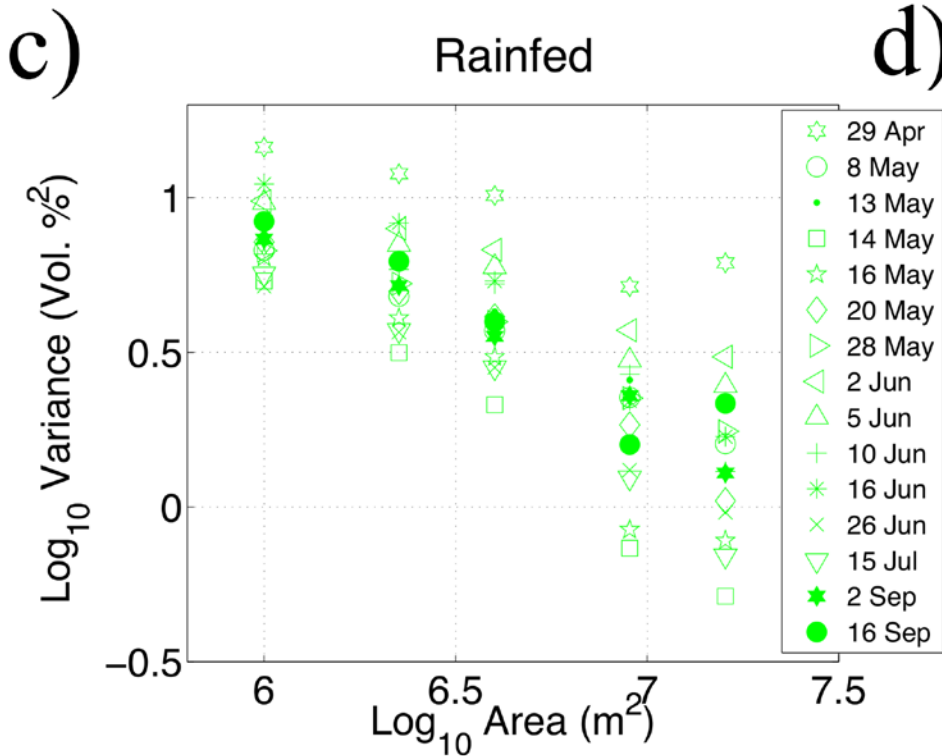
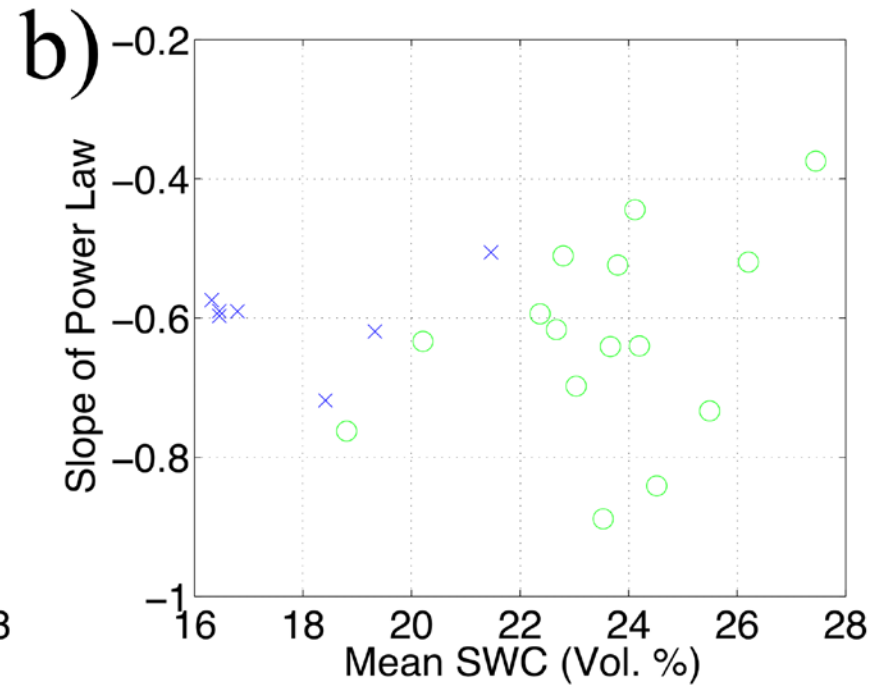
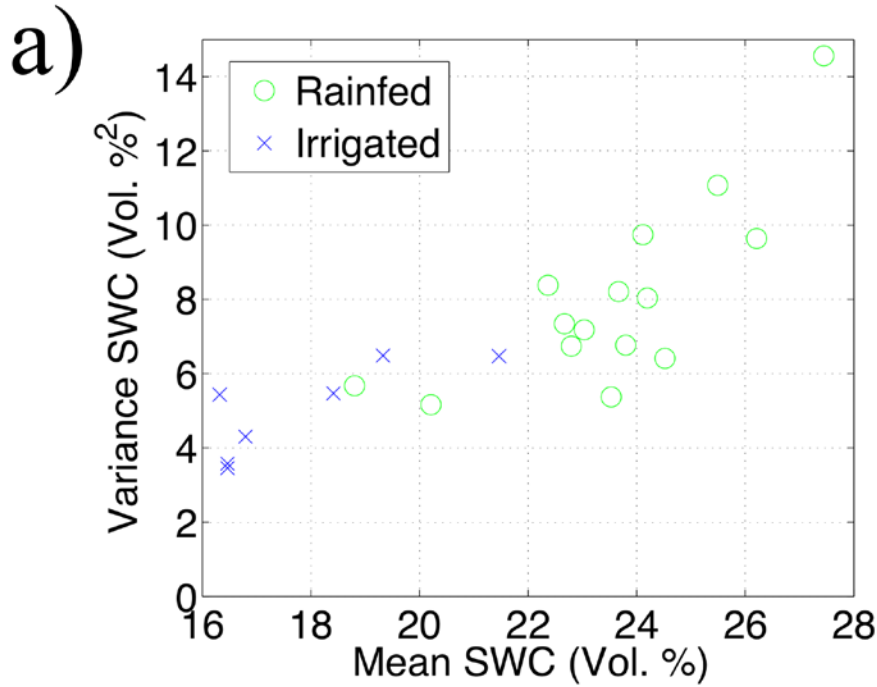
SWC (Vol. %)

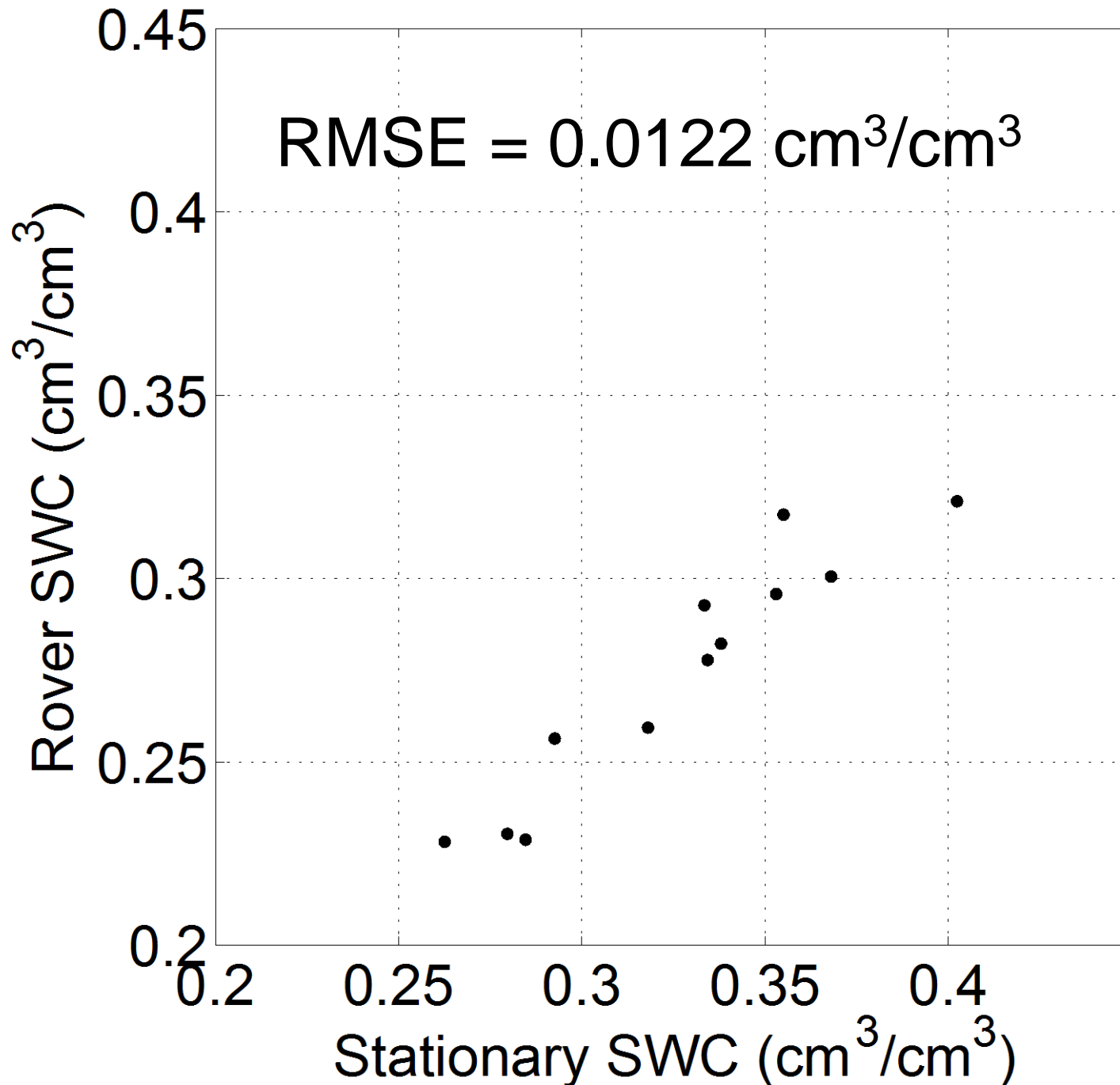


SWC (Vol. %)



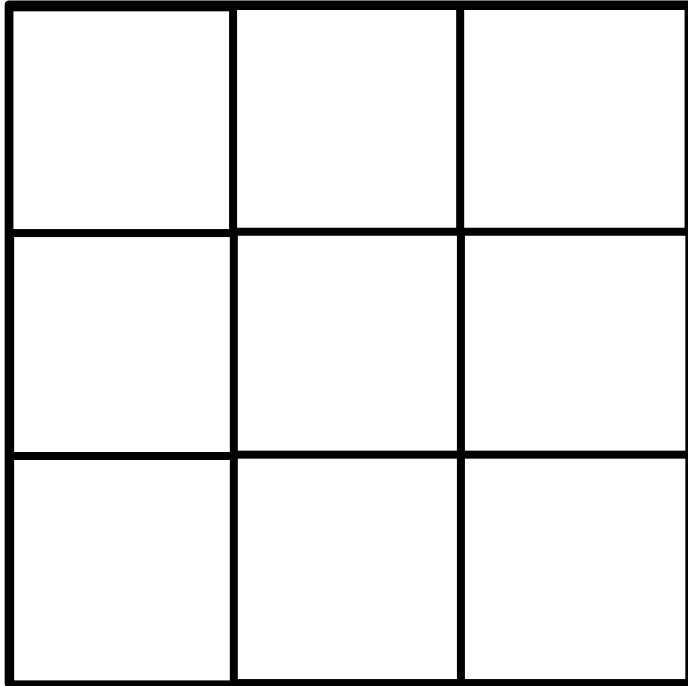




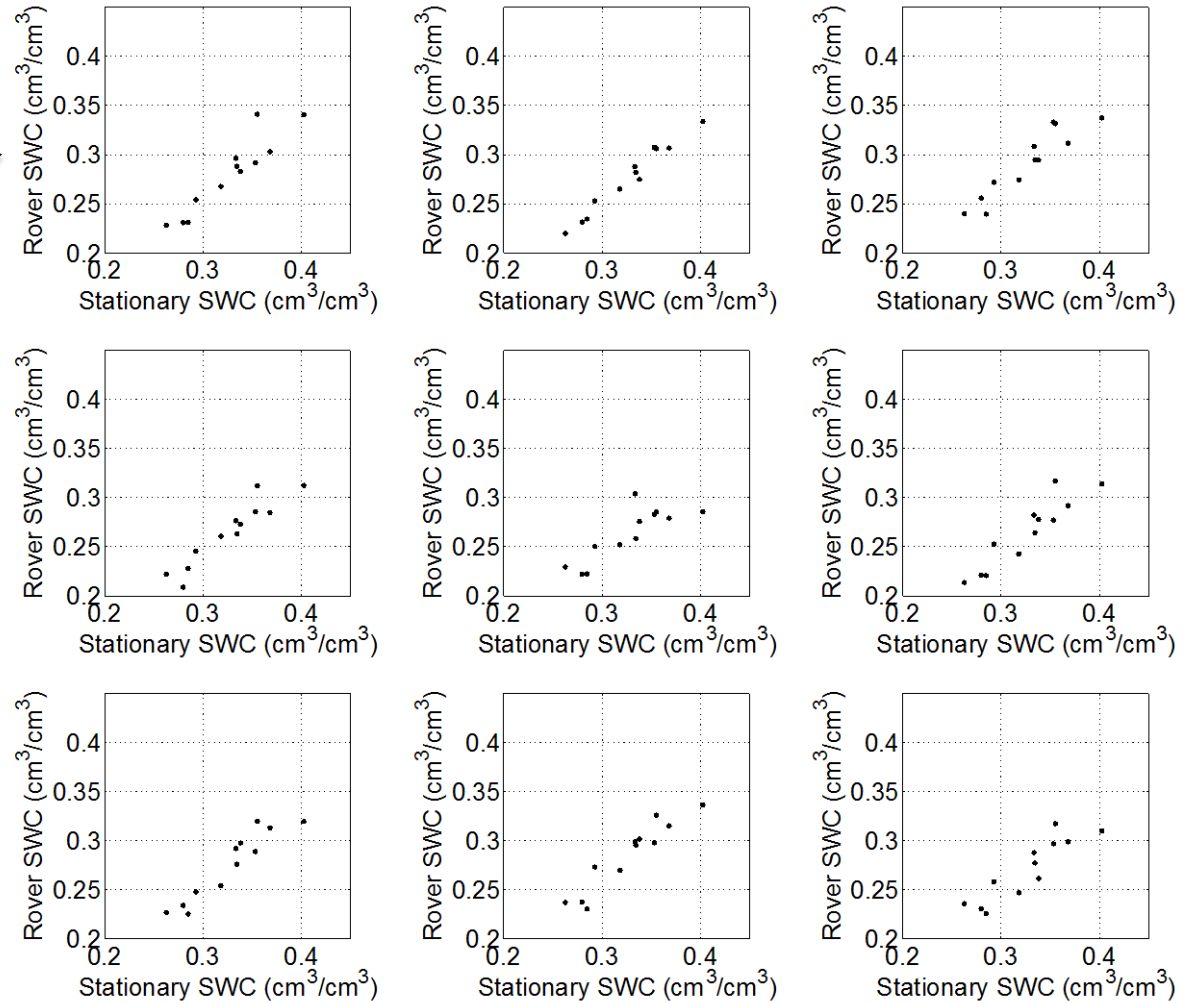
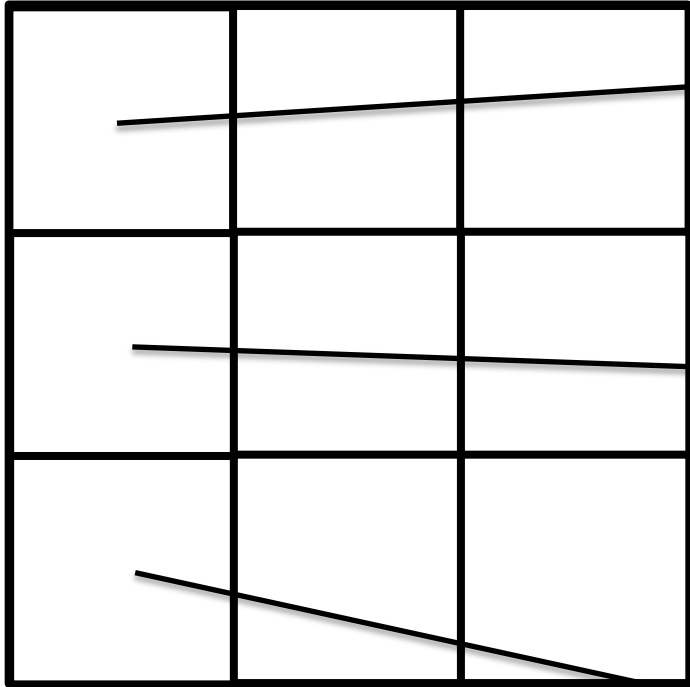


Split 12 km domain into 9 4x4 km subdomains

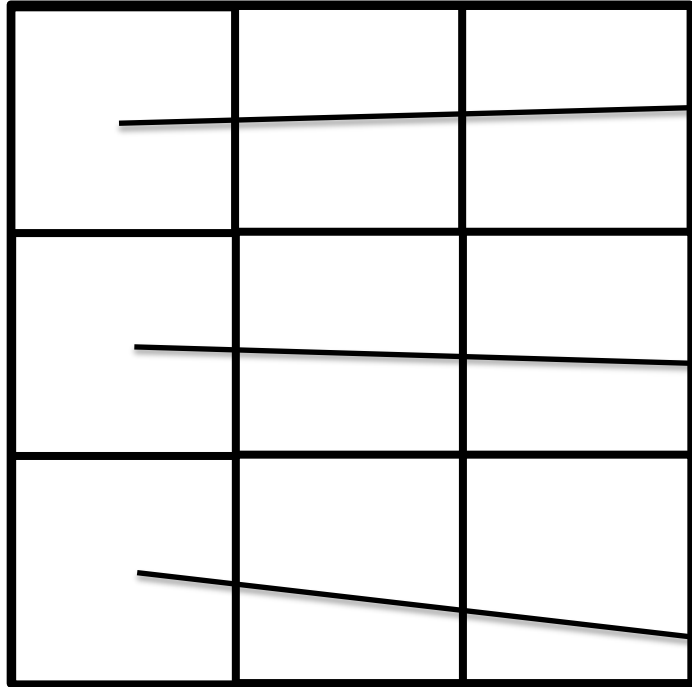
4 km



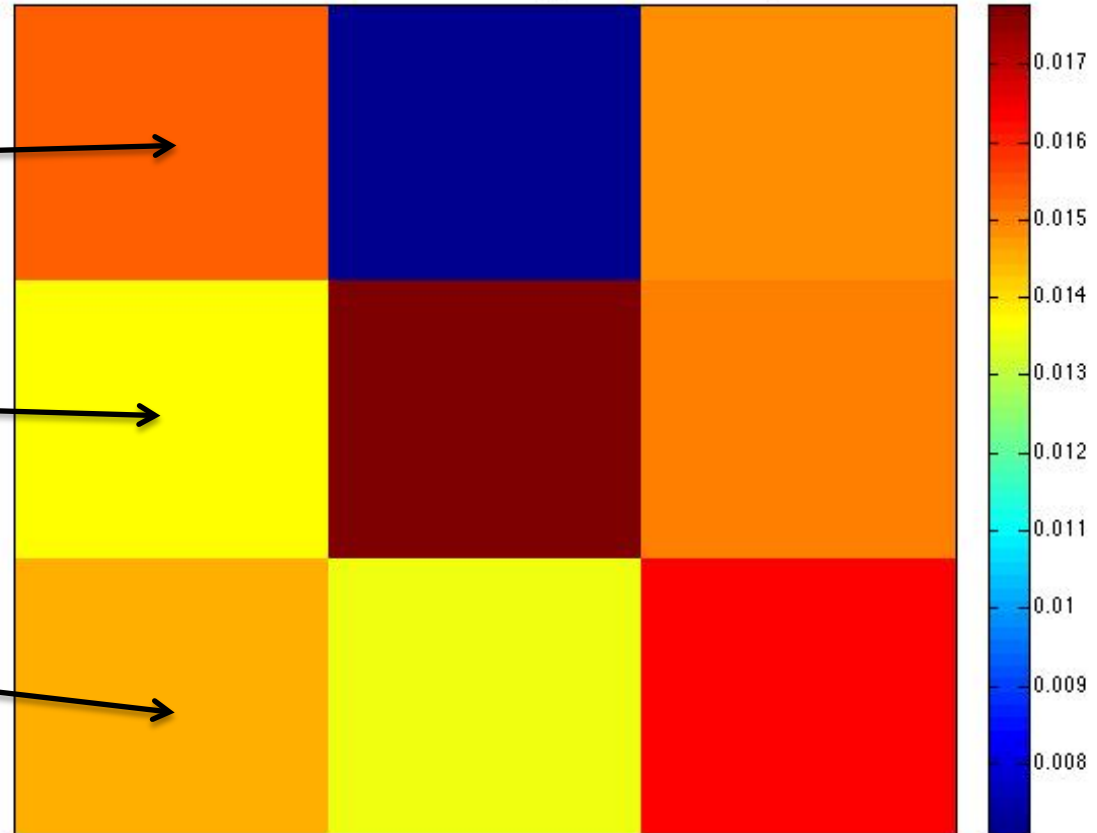
4 km



4 km

Scaled Grid RMSE (cm^3/cm^3)

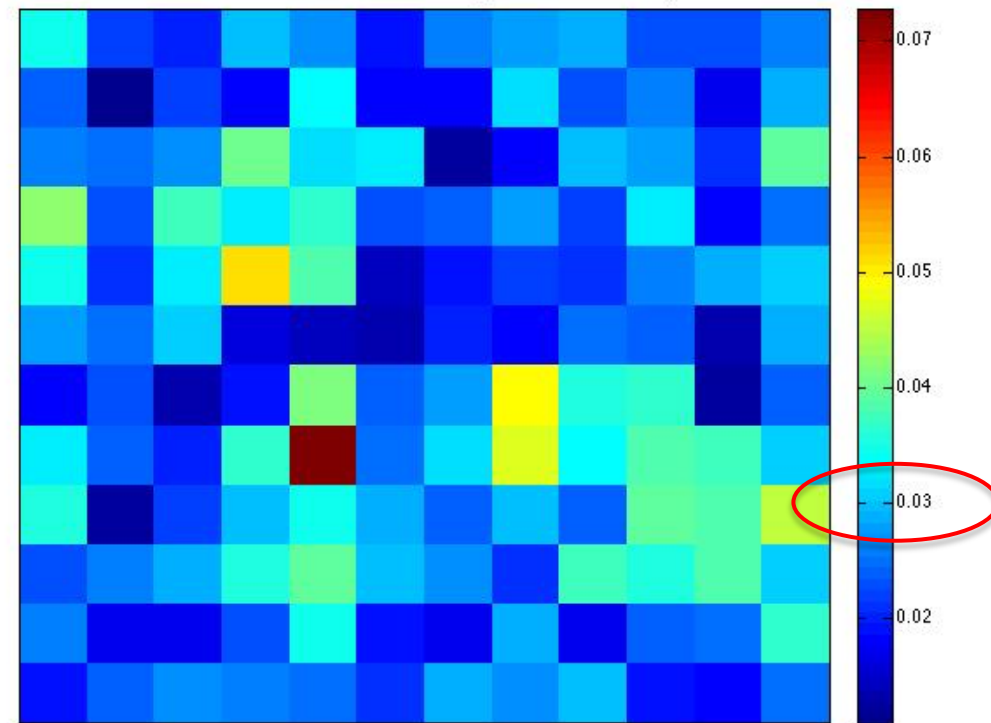


Split 12 km domain into 144 quarter section subdomains



0.8 km

↔ Scaled Grid RMSE (cm^3/cm^3)



- Combined fixed and mobile cosmic-ray probes to provide a realtime SWC monitoring network at ~ 1 km resolutions over a 144 km^2 domain with 3 stationary CRS and 20 CRS rover surveys with $\text{RMSE} < \sim 3\%$
- Rover mapping can provide invaluable information to remote sensing
 - i.e. comparison of mean, relationship between mean and variance, spatial and temporal covariance matrices for downscaling
- Is the network cost effective? Are there better ways to design the network?

VOL. 10, NO. 4

WATER RESOURCES RESEARCH

AUGUST 1974

The Design of Rainfall Networks in Time and Space

IGNACIO RODRÍGUEZ-ITURBE

Department of Civil Engineering, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139

JOSÉ M. MEJÍA

Instituto Venezolano de Investigaciones Científicas, Caracas, Venezuela

3. For estimating long-term areal mean values of precipitation the commanding factor is the length of time that the network has been in operation.
4. Trading time versus space is possible in many cases when long-term areal mean values are estimated. Nevertheless, it is an expensive proposition.

VOL. 10, NO. 4

WATER RESOURCES RESEARCH

AUGUST 1974

The Design of Rainfall Networks in Time and Space

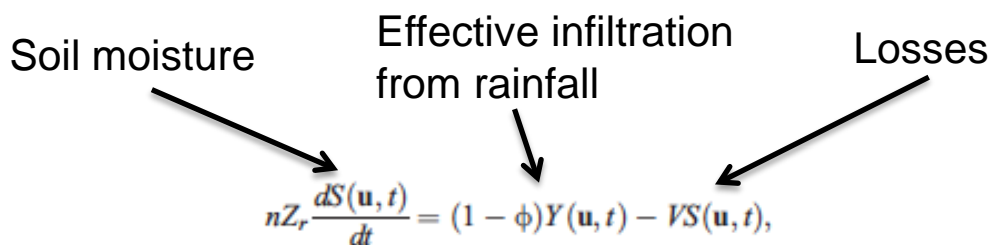
IGNACIO RODRÍGUEZ-ITURBE

Department of Civil Engineering, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139

JOSÉ M. MEJÍA

Instituto Venezolano de Investigaciones Científicas, Caracas, Venezuela

3. For estimating long-term areal mean values of precipitation the commanding factor is the length of time that the network has been in operation.
4. Trading time versus space is possible in many cases when long-term areal mean values are estimated. Nevertheless, it is an expensive proposition.



WATER RESOURCES RESEARCH, VOL. 42, W05409, doi:10.1029/2005WR004548, 2006

On the spatial and temporal sampling of soil moisture fields

Salvatore Manfreda^{1,2} and Ignacio Rodríguez-Iturbe¹

Received 1 September 2005; revised 10 January 2006; accepted 24 January 2006; published 3 May 2006.

greatest gain in information for the estimation of the long-term mean daily soil moisture in a region is obtained with an initial, relatively small, number of stations.

VOL. 10, NO. 4

WATER RESOURCES RESEARCH

AUGUST 1974

The Design of Rainfall Networks in Time and Space

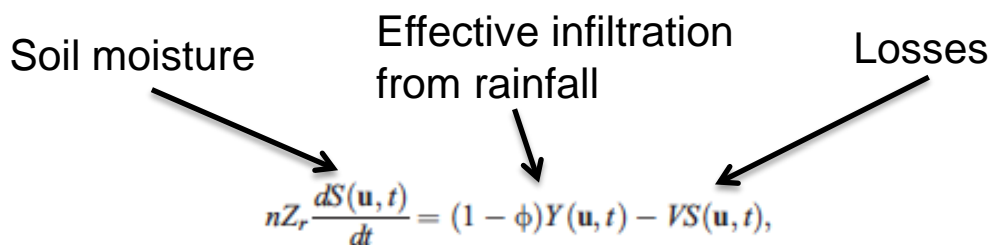
IGNACIO RODRÍGUEZ-ITURBE

Department of Civil Engineering, Massachusetts Institute of Technology, Cambridge, Massachusetts 02139

JOSÉ M. MEJÍA

Instituto Venezolano de Investigaciones Científicas, Caracas, Venezuela

3. For estimating long-term areal mean values of precipitation the commanding factor is the length of time that the network has been in operation.
4. Trading time versus space is possible in many cases when long-term areal mean values are estimated. Nevertheless, it is an expensive proposition.



WATER RESOURCES RESEARCH, VOL. 42, W05409, doi:10.1029/2005WR004548, 2006

On the spatial and temporal sampling of soil moisture fields

Salvatore Manfreda^{1,2} and Ignacio Rodriguez-Iturbe¹

Received 1 September 2005; revised 10 January 2006; accepted 24 January 2006; published 3 May 2006.

WATER RESOURCES RESEARCH, VOL. 42, W06D05, doi:10.1029/2005WR004497, 2006

greatest gain in information for the estimation of the long-term mean daily soil moisture in a region is obtained with an initial, relatively small, number of stations.

[63] The standard deviation of the averaged relative soil moisture is particularly sensitive to the averaging spatial scale. Averaging in space considerably smoothes the relative soil moisture process; this effect depends on the vegetation characteristics (small scale) and the structure of the rainfall process (large scale). By contrast, averaging in

[64] Comparison of the derived analytical results with the space-time correlation structure of soil moisture fields is a research priority of the authors. We are not aware of empirical soil moisture data available in space and time that will enable a strict validation of the theory. For this

Space-time modeling of soil moisture: Stochastic rainfall forcing with heterogeneous vegetation

I. Rodriguez-Iturbe,¹ V. Isham,² D. R. Cox,³ S. Manfreda,^{1,4} and A. Porporato⁵

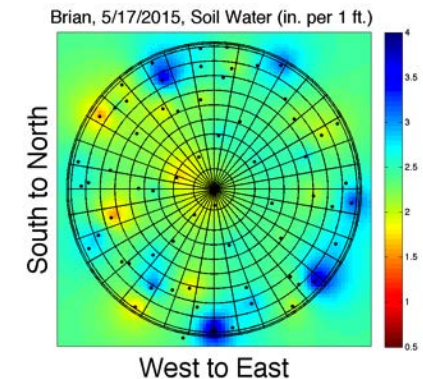
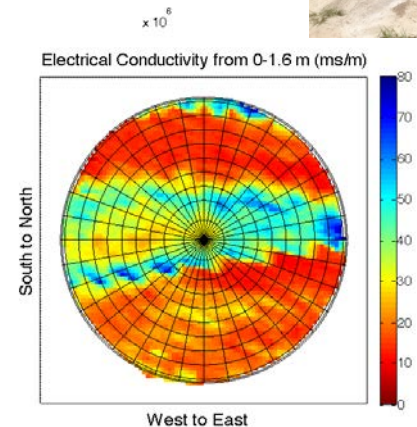
Precision Agriculture

- Install network of 3-5 inexpensive point sensor profiles (1, 2, 3 ft.) with realtime data



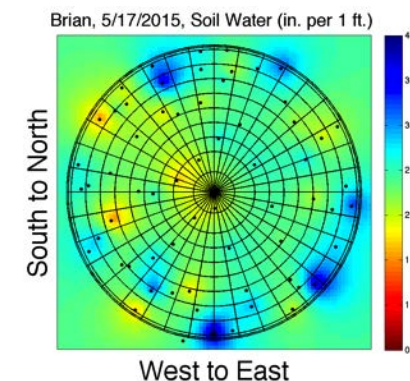
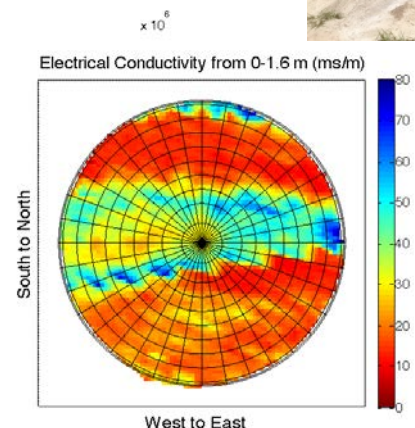
Precision Agriculture

- Install network of 3-5 inexpensive point sensor profiles (1, 2, 3 ft.) with realtime data
- Map field with CREMISS for texture and soil moisture spatial patterns
- Map field 4-6 more times with CR rover to form spatial calibration functions



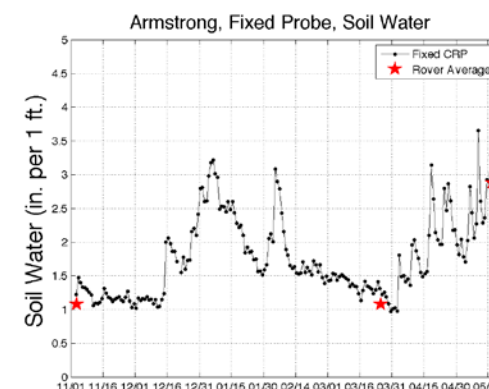
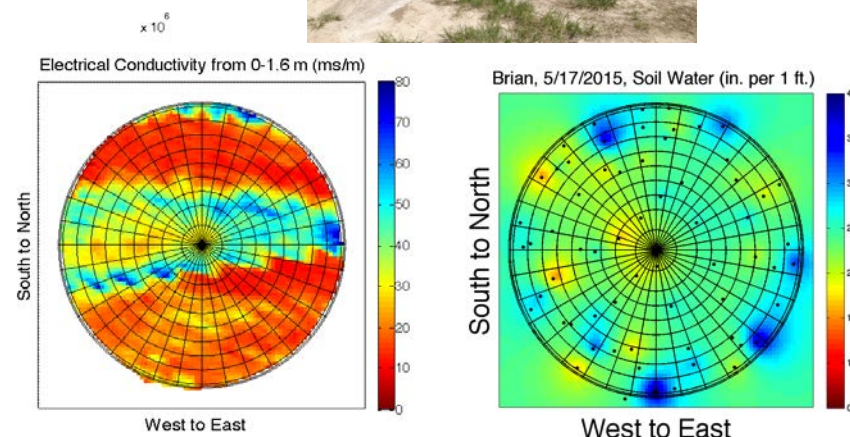
Precision Agriculture

- Install network of 3-5 inexpensive point sensor profiles (1, 2, 3 ft.) with realtime data
- Map field with CREMISS for texture and soil moisture spatial patterns
- Map field 4-6 more times with CR rover to form spatial calibration functions
- Incorporate exponential filters for depth estimates down to 3 ft.

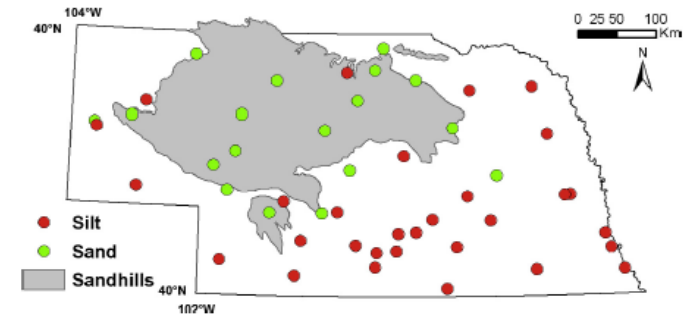


Precision Agriculture

- Install network of 3-5 inexpensive point sensor profiles (1, 2, 3 ft.) with realtime data
- Map field with CREMISS for texture and soil moisture spatial patterns
- Map field 4-6 more times with CR rover to form spatial calibration functions
- Incorporate exponential filters for depth estimates down to 3 ft.
- Provide realtime SWC statistical estimates by pivot section and 1 ft. depth increments by combining point sensor information with CREMISS mapping, spatial regression, and exponential filters

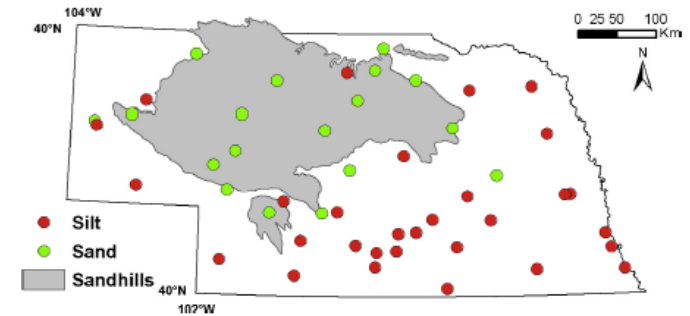


Integration with Mesonets



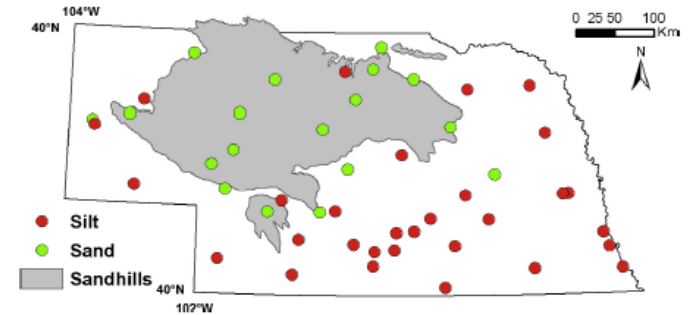
- Map areas with rover around longterm stations (SCAN, ADWN, OK. Mesonet, etc.), 10-15 times?

Integration with Mesonets



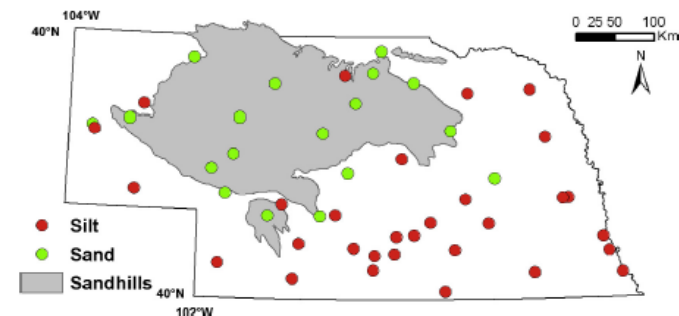
- Map areas with rover around longterm stations (SCAN, ADWN, OK. Mesonet, etc.), 10-15 times?
- Investigate spatial calibration functions between rover and longterm station values (0-30 cm avg.)

Integration with Mesonets



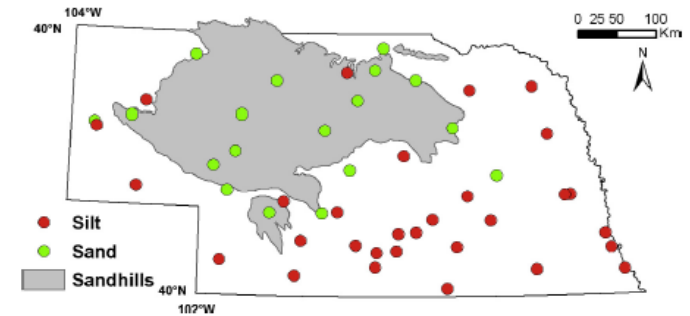
- Map areas with rover around longterm stations (SCAN, ADWN, OK. Mesonet, etc.), 10-15 times?
- Investigate spatial calibration functions between rover and longterm station values (0-30 cm avg.)
- Incorporate texture, elevation, vegetation characteristics, in geostatistical/data mining analyses

Integration with Mesonets



- Map areas with rover around longterm stations (SCAN, ADWN, OK. Mesonet, etc.), 10-15 times?
- Investigate spatial calibration functions between rover and longterm station values (0-30 cm avg.)
- Incorporate texture, elevation, vegetation characteristics, in geostatistical/data mining analyses
- Use statistical models to provide realtime spatial estimates of landscape scale soil moisture patterns

Integration with Mesonets



- Map areas with rover around longterm stations (SCAN, ADWN, OK. Mesonet, etc.), 10-15 times?
- Investigate spatial calibration functions between rover and longterm station values (0-30 cm avg.)
- Incorporate texture, elevation, vegetation characteristics, in geostatistical/data mining analyses
- Use statistical models to provide realtime spatial estimates of landscape scale soil moisture patterns
- Historical reconstruction of soil moisture fields for LSM initial conditions, LSM validation, and/or remote sensing analyses?



See posters by Will and Catie tomorrow on CRS vegetation and soil calibration using remote sensing and global databases.

This work is supported by:

- NSF EPSCoR FIRST Award
- Cold Regions Research and Engineering Lab through the CESU
- USGS104b
- Layman Award